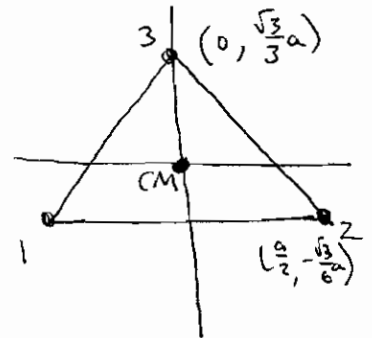


PHY 504 Problem Set #10 Solutions

1. Omitted. See example p. 253.

2. Arrange the masses as shown with the center of mass at the origin. Let $\vec{r}_{10}, \vec{r}_{20}, \vec{r}_{30}$ be the equilibrium positions, and let η_k



and ξ_k be the deviations from equilibrium in the x - and y -directions, respectively.

Then

$$L = \frac{1}{2} m (\dot{\vec{r}}_1^2 + \dot{\vec{r}}_2^2 + \dot{\vec{r}}_3^2) - \frac{1}{2} k [(r_{12} - a)^2 + (r_{23} - a)^2 + (r_{31} - a)^2]$$

First look at the kinetic energy. Impose the CM constraint $\vec{r}_1 + \vec{r}_2 + \vec{r}_3 = 0 \Rightarrow \dot{\vec{r}}_3 = -\dot{\vec{r}}_1 - \dot{\vec{r}}_2$:

$$T = \frac{1}{2} m (\dot{\vec{r}}_1^2 + \dot{\vec{r}}_2^2 + (\dot{\vec{r}}_1 + \dot{\vec{r}}_2)^2) = m (\dot{\vec{r}}_1^2 + \dot{\vec{r}}_2^2 + \dot{\vec{r}}_1 \cdot \dot{\vec{r}}_2)$$

$$= m (\dot{\eta}_1^2 + \dot{\xi}_1^2 + \dot{\eta}_2^2 + \dot{\xi}_2^2 + \dot{\eta}_1 \dot{\eta}_2 + \dot{\xi}_1 \dot{\xi}_2)$$

$$\equiv \frac{1}{2} T_{ij} \dot{q}_i \dot{q}_j$$

where

$$T_{ij} = m \begin{pmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{pmatrix} = \begin{pmatrix} \eta_1 \\ \eta_2 \\ \xi_1 \\ \xi_2 \end{pmatrix}$$

Potential energy:

$$\begin{aligned}
 V &= \frac{1}{2} k \left[\left(\sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2} - a \right)^2 + \text{cyclic} \right] \\
 &= \frac{1}{2} k \left[\left(\sqrt{\left(a + r_1 - r_2 \right)^2 + \left(\rho_1 - \rho_2 \right)^2} - a \right)^2 \right. \\
 &\quad + \left(\sqrt{\left(\frac{a}{2} + r_2 - r_3 \right)^2 + \left(-\frac{\sqrt{3}}{2} + \rho_2 - \rho_3 \right)^2} - a \right)^2 \\
 &\quad \left. + \left(\sqrt{\left(\frac{a}{2} + r_3 - r_1 \right)^2 + \left(\frac{\sqrt{3}}{2} + \rho_3 - \rho_1 \right)^2} - a \right)^2 \right] \\
 &= \frac{1}{2} k a^2 \left[\left(\sqrt{\left(1 + \frac{r_1 - r_2}{a} \right)^2 + \left(\frac{\rho_1 - \rho_2}{a} \right)^2} - 1 \right)^2 \right. \\
 &\quad + \left(\sqrt{\left(\frac{1}{2} + \frac{r_2 - r_3}{a} \right)^2 + \left(-\frac{\sqrt{3}}{2} + \frac{\rho_2 - \rho_3}{a} \right)^2} - 1 \right)^2 \\
 &\quad \left. + \left(\sqrt{\left(\frac{1}{2} + \frac{r_3 - r_1}{a} \right)^2 + \left(\frac{\sqrt{3}}{2} + \frac{\rho_3 - \rho_1}{a} \right)^2} - 1 \right)^2 \right] \\
 &= \frac{1}{2} k a^2 \left[\left[-\frac{(r_1 - r_2)}{a} \right]^2 + \left[\frac{r_2 - r_3}{2a} - \sqrt{3} \frac{\rho_2 - \rho_3}{2a} \right]^2 \right. \\
 &\quad \left. + \left[\frac{r_3 - r_1}{2a} + \sqrt{3} \frac{\rho_3 - \rho_1}{2a} \right]^2 \right] \\
 &= \frac{1}{2} k \cdot \left\{ r_1^2 - 2r_1 r_2 + r_2^2 + \frac{1}{4} (r_2^2 - 2r_2 r_3 + r_3^2) + \frac{3}{4} (\rho_2^2 - 2\rho_2 \rho_3 + \rho_3^2) \right. \\
 &\quad \left. - \frac{\sqrt{3}}{2} (r_2 \rho_2 - r_2 \rho_3 - r_3 \rho_2 + r_3 \rho_3) \right. \\
 &\quad \left. + \frac{1}{4} (r_3^2 - 2r_3 r_1 + r_1^2) + \frac{3}{4} (\rho_3^2 - 2\rho_3 \rho_1 + \rho_1^2) + \frac{\sqrt{3}}{2} (r_3 \rho_3 - r_3 \rho_1 - r_1 \rho_3 + r_1 \rho_1) \right\}
 \end{aligned}$$

$$= \frac{1}{2} k \left\{ \begin{aligned} & \eta_1^2 - 2\eta_1\eta_2 + \eta_2^2 \\ & + \frac{1}{4}\eta_1^2 + \eta_1\eta_2 + \eta_2^2 + 3S_1^2 + 12S_1S_2 + 12S_2^2 - 2\sqrt{3}\eta_1S_1 - 4\sqrt{3}\eta_1S_2 - 4\sqrt{3}\eta_2S_1 - 8\sqrt{3}\eta_2S_2 \\ & + \eta_1^2 + \eta_1\eta_2 + \frac{1}{4}\eta_2^2 + 12S_1^2 + 12S_1S_2 + 3S_2^2 + 8\sqrt{3}\eta_1S_1 + 4\sqrt{3}\eta_1S_2 + 4\sqrt{3}\eta_2S_1 + 2\sqrt{3}\eta_2S_2 \end{aligned} \right\}$$

So $V = \frac{1}{2} V_{ij} q_i q_j$ where

$$V_{ij} = k \begin{pmatrix} \frac{9}{4} & 0 & \frac{3\sqrt{3}}{4} & 0 \\ 0 & \frac{9}{4} & 0 & -\frac{3\sqrt{3}}{4} \\ \frac{3\sqrt{3}}{4} & 0 & \frac{15}{4} & 3 \\ 0 & -\frac{3\sqrt{3}}{4} & 3 & \frac{15}{4} \end{pmatrix}$$

The equations of motion are

$$T_{ij} \ddot{q}_j = -V_{ij} q_j$$

If $q_j(t)$ is a normal mode of frequency ω , then $\ddot{q}_j = -\omega^2 q_j$,

so
$$-\omega^2 T_{ij} q_j = -V_{ij} q_j \quad \text{or} \quad (T^{-1}V)_{ij} q_j = \omega^2 q_i$$

In other words, the normal mode frequencies are the eigenvalues of $T^{-1}V$. T is block-diagonal, so it's easy to invert: just invert the 2×2 blocks to get

$$T^{-1} = \frac{1}{3m} \begin{pmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{pmatrix}$$

Then

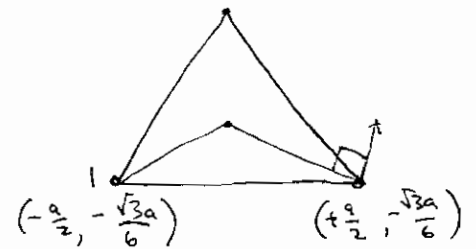
$$T^{-1}V = \frac{k}{3m} \begin{pmatrix} \frac{9}{2} & -\frac{9}{4} & \frac{3\sqrt{3}}{2} & \frac{3\sqrt{3}}{4} \\ -\frac{9}{4} & \frac{9}{2} & -\frac{3\sqrt{3}}{4} & -\frac{3\sqrt{3}}{2} \\ \frac{3\sqrt{3}}{2} & \frac{3\sqrt{3}}{4} & \frac{9}{2} & \frac{9}{4} \\ -\frac{3\sqrt{3}}{4} & -\frac{3\sqrt{3}}{2} & \frac{9}{4} & \frac{9}{2} \end{pmatrix}$$

The eigenvalues of this matrix are (from Mathematica!)

$$\omega^2 = 0, \underbrace{\frac{3k}{m}, \frac{3k}{2m}, \frac{3k}{2m}}_{\text{double}}$$

The rotational mode about the origin is generated by the infinitesimal transformation

$$\begin{aligned} x &\rightarrow x - \epsilon y \\ y &\rightarrow y + \epsilon x \end{aligned}$$



At vertex 1, this corresponds to $q_1 = -\epsilon y_{10} = +\epsilon \frac{\sqrt{3}}{6} a$ $\int_1 = +\epsilon x_{10} = -\epsilon \frac{a}{2}$

At vertex 2, $q_2 = \epsilon \frac{\sqrt{3}}{6} a$ and $\int_2 = +\epsilon \frac{a}{2}$.

The rotational mode is generated by the column vector

$$q_i = \frac{\epsilon a}{6} \begin{pmatrix} \sqrt{3} \\ +\sqrt{3} \\ -3 \\ 3 \end{pmatrix}$$

It is easily checked that this is an eigenvector of

$T^{-1}V$ with eigenvalue 0.

Similarly, uniform stretching is generated by

$$q_i = \frac{\epsilon a}{6} \begin{pmatrix} 3 \\ -3 \\ \sqrt{3} \\ \sqrt{3} \end{pmatrix}$$

The corresponding eigenvalue is $\frac{3k}{m}$.