## University of Kentucky, Physics 306 Homework #8, Rev. D, due Monday, 2022-04-04

1. The gradient, curl, and divergence are all applications of d in different dimensions. They are defined as  $df = \nabla f \cdot dl$ ,  $d(\mathbf{A} \cdot d\mathbf{l}) = (\nabla \times \mathbf{A}) \cdot d\mathbf{a}$ ,  $d(\mathbf{B} \cdot d\mathbf{a}) = (\nabla \cdot \mathbf{B}) \cdot d\tau$ , respectively, in terms of the differential operator  $d = dq^i \partial_i$  and elements  $d\mathbf{l} = \hat{\mathbf{e}}_i h_i dq^i$ ,  $d\mathbf{a} = \frac{1}{2} d\mathbf{l} \times d\mathbf{l}$ ,  $d\tau = \frac{1}{3} d\mathbf{l} \cdot d\mathbf{a}$ .

a) Apply these definitions to generic fields to obtain the formulas

$$\boldsymbol{\nabla} f = \frac{\hat{\boldsymbol{e}}_i}{h_i} \frac{\partial}{\partial q^i} f, \quad \boldsymbol{\nabla} \times \boldsymbol{A} = \frac{\hat{\boldsymbol{e}}_i}{h_j h_k} \frac{\partial}{\partial q^j} h_k A_k, \quad \boldsymbol{\nabla} \cdot \boldsymbol{B} = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial q^k} h_i h_j B_k, \quad \text{for } i, j, k \text{ cyclic}$$

**b**) Expand these formulas in Cartesian, cylindrical, and spherical coordinates and compare your results with Wikipedia: Del in cylindrical and spherical coordinates.

- c) Calculate the gradient of  $f(r, \theta, \phi) = r^{\ell} P_{\ell}(\cos(\theta))$ , using  $\frac{x^2 1}{\ell} P'_{\ell}(x) = x P_{\ell}(x) P_{\ell-1}(x)$ .
- d) Calculate the curl of  $\mathbf{A}(x, y, z) = (\hat{\mathbf{y}}x \hat{\mathbf{x}}y)/(x^2 + y^2)^n$  in Cartesian and cylindrical coordinates.

e) Calculate the divergence of  $\boldsymbol{B}(x,y,z) = (\hat{\boldsymbol{x}}x + \hat{\boldsymbol{y}}y + \hat{\boldsymbol{z}}z)/(x^2 + y^2 + z^2)^n$  in Cartesian and spherical coordinates.

**f**) Derive the formulas for  $d^2 f$  and  $d^2 \mathbf{A} \cdot d\mathbf{l}$  in terms of their partial derivatives to show that the trivial 2<sup>nd</sup> derivatives  $\nabla \times \nabla f$  and  $\nabla \cdot \nabla \times \mathbf{A}$  are special cases of  $d^2 = 0$ .

**2.** Potential theory—the Fundamental Theorem of Differentials (FTD)  $d \int_r \omega + \int_r d\omega = \omega$  implies that if  $d\omega = 0$ , then the potential  $\alpha \equiv \int_r \omega \equiv \left[\int_{r'=0}^r \omega_{r\Omega}(r',\Omega)dr'\right] d\Omega$  (integrated along radial coordinate lines) is its antiderivative:  $d\alpha = \omega$ . We will use this formula to derive the antiderivative of the following special vector fields, generalizing the Fundamental Theorem of Calculus (FTC):

a) Show that if  $\nabla \times E = 0$  (ie. *E* is *irrotational*), then  $E = -\nabla V$  (ie. *E* is *conservative*), with the potential function  $V(\mathbf{r}) = -\int_{\mathbf{r}} E \cdot d\mathbf{l} + C$ , where *C* is any constant. Show that for a radial path in spherical coordinates, this reduces to  $\mathbf{V} = -\mathbf{r} \cdot \int_{0}^{1} E(\lambda \mathbf{r}) d\lambda$ .

b) Show that if  $\nabla \cdot \boldsymbol{B} = 0$  (ie.  $\boldsymbol{B}$  is *incompressible*), then  $\boldsymbol{B} = \nabla \times \boldsymbol{A}$  (ie.  $\boldsymbol{B}$  is *solenoidal*), with the potential function  $\boldsymbol{A} \cdot \boldsymbol{dl} = \int_r \boldsymbol{B} \cdot \boldsymbol{da} + d\chi$ , where the 'constant of integration'  $d\chi$  is the differential of any scalar field. Show that for a radial path in spherical coordinates, this reduces to  $\boldsymbol{A} = -\boldsymbol{r} \times \int_0^1 \lambda B(\lambda \boldsymbol{r}) d\lambda$ .

c) [bonus: Show that since the differential of any density field  $\rho(\mathbf{r})d\tau$  is zero, it can be writen as the exact differential  $\rho = \nabla \cdot (\mathbf{B} + \nabla \times \mathbf{A})$  of some flux field  $\mathbf{B}(\mathbf{r}) \cdot d\mathbf{a}$ , and any constant of integration (gauge)  $\mathbf{A}(\mathbf{r}) \cdot d\mathbf{l}$ . Derive the formula for  $\mathbf{B}$  for a radial path in spherical coordinates.]

**3.** Stokes' theorems—the FTD also generalizes the FTC, integrating the derivative of a field over a region out to the boundary, resulting in an integral of the original field on the boundary.

**a)** Integrate  $\mathcal{S} \int \nabla \times \boldsymbol{v} \cdot \boldsymbol{da}$  where  $\boldsymbol{v} = \hat{\boldsymbol{x}} x^2 + \hat{\boldsymbol{y}} 2yz + \hat{\boldsymbol{z}} xy$ , and  $\mathcal{S}$  is the parallelogram in the figure to the right. Integrate  $\partial \mathcal{S} \oint \boldsymbol{v} \cdot \boldsymbol{dl}$  along the boundary  $\partial S$  of  $\mathcal{S}$  to verify Stokes' theorem.

**b)** Verify Stoke's theorem with the function in #1d) on the disk  $\rho < R, z = 0$  in the *xy*-plane centered at the origin.

c) Verify Gauss' theorem with the function in #1e) inside the sphere r < R of radius R centered at the origin.

