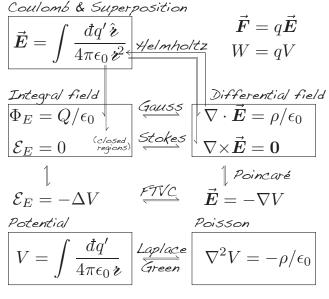
Section 5.3 - Div and Curl of B

st the formalism of both electrostatics and magnetostatics follow the Helmholtz theorem

* these two diagrams illustrate the symmetry between the two forces



* derivative
$$\bigvee \overset{-\mathbb{V}}{\rightarrow} \overset{\overset{\bullet}{\vdash}}{\vdash} \overset{\mathbb{V}}{\rightarrow} \bigcirc$$

chains

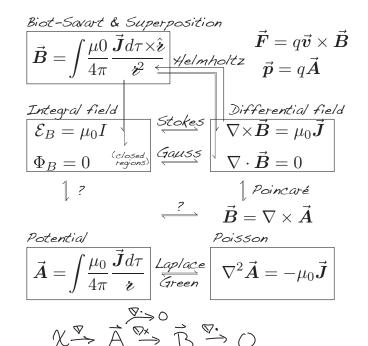
 $\varepsilon \lor$
 $\widetilde{\mathbb{D}} \overset{\overset{\bullet}{\rightarrow}}{\rightarrow} \rho$

B=Stataxx元

* integral equations

$$\mathcal{E}_{B} = \mathcal{G}\vec{B}\cdot\vec{dl} = \nu_{o}\mathcal{I}\mathcal{G}\frac{sd\phi}{2\pi S} = \nu_{s}\mathcal{I}\mathcal{G}\frac{d\phi}{2\pi} = \nu_{o}\mathcal{I}$$

~ assumes exactly I winding, otherwise, NoNI



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* differential equations (note: do = J'du or R'du or I'di)

$$= \nabla \times \int \frac{\partial \vec{a}}{\partial t}$$

$$= \nabla \times \vec{A} \qquad \vec{A} = \int \frac{\partial \vec{a}}{\partial t}$$

$$= \nabla \times \vec{A} \qquad \vec{A} = \int \frac{\partial \vec{a}}{\partial t}$$

$$\nabla \cdot \vec{B} = \nabla \cdot \nabla \times \vec{A} = 0 \qquad \Leftrightarrow \qquad \int \frac{\partial \vec{a}}{\partial t}$$

$$\vec{E}_{B} = \int \vec{B} \cdot d\vec{a} = \int \vec{\nabla} \cdot \vec{B} \, d\vec{t} = 0$$

$$\nabla \times \vec{B} = \nabla \times (\nabla \times \vec{A}) = \nabla (\nabla \cdot \vec{A}) - \nabla^{2} \vec{A} = \mu_{0} \vec{J}$$

$$-\nabla^{2} \vec{A} = -\nabla^{2} \int \frac{\partial \vec{a}}{\partial t} = \int \mu_{0} d\vec{a} = \int \mu_{0} d\vec{a} = \int \mu_{0} \vec{J} (\vec{r}) \, d\vec{t} = \int \mu_{0} \vec{J} (\vec{r}) \, d\vec{t} = \int \mu_{0} \vec{J} (\vec{r}) \, d\vec{t} = \int \mu_{0} \vec{J} \cdot d\vec{a} = \mu_{0} \vec{J} \cdot d\vec{a} =$$

$$\nabla \cdot \vec{A} = \nabla \cdot \int \frac{\partial \vec{q}}{\partial \tau} \cdot \nabla \frac{\partial \vec{q}}{\partial \tau}$$

$$= \frac{\mu_0}{4\pi} \int \frac{\partial \vec{q}}{\partial \tau} \cdot \nabla \frac{\partial \vec{q}}{\partial \tau} \cdot \nabla \frac{\partial \vec{q}}{\partial \tau} = 0$$

$$= \frac{\mu_0}{4\pi} \int \frac{\partial \vec{r}}{\partial \tau} \cdot \nabla \frac{\partial \vec{r}}{\partial \tau} \cdot \nabla \frac{\partial \vec{r}}{\partial \tau} = 0$$

$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{J}'G) = 0$$

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$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{J}'G) = 0$$

$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{J}'G) = 0$$

$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{r} \cdot (\vec{r}'G) + 0$$

$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{r}'G) = 0$$

$$= \int \frac{\partial \vec{r}}{\partial \tau} \cdot (\vec{r}'G) = 0$$

Applications of Ampere's law

- * Ampere's law is the analog of Gauss' law for magnetic fields
 - ~ uses a path integral around closed loop instead of integral over a closed surface
 - ~ Simplest way to solve magnetic fields with high symmetry

* Example 5.7: Straight wire

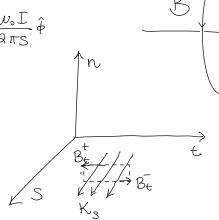
$$\widehat{\mathbf{J}}\widehat{\mathbf{B}}\cdot\widehat{\mathbf{J}} = \mathbf{B}_{\mathbf{b}}\cdot 2\pi\mathbf{S} = \mu_{\mathbf{b}}\mathbf{I} \qquad \widehat{\mathbf{B}} = \underbrace{\mu_{\mathbf{b}}\mathbf{I}}_{\mathbf{a}\pi\mathbf{S}}\widehat{\mathbf{b}}$$

$$\vec{B} = \underbrace{\nu_o I}_{a \pi s} \hat{\phi}$$

* Example 5.8: current septum

$$\oint \vec{B} \cdot \vec{Al} = (-B_{t}^{\dagger} + B_{t}^{-}) l = \mu_{0} K_{s} l = \mu_{0} I$$

$$\hat{n} \times \Delta \vec{B}_{t} = \vec{K} \quad \text{i.e.} \quad B_{t}^{\pm} = \pm \frac{1}{2} K_{s} \hat{b}$$



* Example 5.9: infinite solenoid ~ winding density w = #turns / length

$$K = N \frac{I}{l} = In$$

$$\widehat{\mathcal{G}}\widehat{\mathcal{B}}\widehat{\mathcal{A}}\widehat{\mathcal{I}} = (B_z - B_z) \cdot L = 0$$
 out side.
 $\widehat{\mathcal{G}}\widehat{\mathcal{B}}\widehat{\mathcal{A}}\widehat{\mathcal{I}} = (B_z - B_z) \cdot L = \mu_0 K L$ $\Delta B = \mu_0 K \text{ again}!$

* Maxwell's equations (steady-state E&M)

$$\nabla \cdot \vec{E} = P_{\mathcal{E}}$$
 $\nabla \cdot \vec{B} = 0$
 $\nabla_{x} \vec{E} = 0$ $\nabla_{x} \vec{B} = \mu_{o} \vec{J}$
 $\vec{F} = Q (\vec{E} + \vec{v}_{x} \vec{B})$

- ~ the two zeros mean there is no magnetic monopole
- ~ actually as long as 4/9 is constant, a magnetic monopole can turned into an electric charge by a redefinition of E and B (duality rotation)