University of Kentucky, Physics 335 Homework #3, Rev. C, due Thursday, 2021-11-03

1. The asymmetry $A = \frac{a-b}{a+b}$ is a convenient dimensionless parameter quantifying the relative difference between two positive observables a and b. It ranges from a maximum of A = 1 if $a \gg b$ to A = 0 if a = b to the minimum value A = -1 if $a \ll b$. It is also used to describe the polarization $P = \frac{N_{+} - N_{-}}{N_{+} + N_{-}}$ of a two-state species with N_{+} particles in one [spin] state and N_{-} in the other.

a) Calculate the uncertainty δA of A in terms of the covariance matrix $\delta^2 v_{ij}$ of $\vec{v} = (a, b)$ with elements $\delta_a^2 \equiv \text{Cov}(a, a) = \text{Var}(a)$, $\delta_{ab}^2 \equiv \text{Cov}(a, b) = \delta_{ba}^2$, and $\delta_b^2 \equiv \text{Cov}(b, b) = \text{Var}(b)$, using the error propagation formula $\delta^2 A_{\alpha\beta}(\vec{v}) = \sum_{i,j} \frac{\partial A_{\alpha}}{\partial v_i} \frac{\partial A_{\beta}}{\partial v_j} \delta^2 v_{ij}$ or $\delta^2 A = J \delta^2 v J^T$, where $J_{\alpha i} = \frac{\partial A_{\alpha}}{\partial v_i}$. For a single function $A(\vec{v})$, this reduces to the variance $\delta^2 A = (\frac{\partial A}{\partial a})^2 \delta_a^2 + 2(\frac{\partial A}{\partial a})(\frac{\partial A}{\partial b}) \delta_{ab}^2 + (\frac{\partial A}{\partial b})^2 \delta_b^2$.

b) For extra practice and to verify the consistency of error propagation, Build up the same formula piece by piece, deriving and using the following rules, including full covariance:

- 1. $\delta^2(u\pm v)=\delta^2_u\pm 2\delta^2_{uv}+\delta^2_v, \text{ and } \delta^2(u+v,u-v)=\delta^2_u-\delta^2_v.$
- 2. $\delta^2(\ln u) = \delta_u^2/u^2$ and $\delta^2(\ln u, \ln v) = \delta_{uv}^2/uv$.
- 3. $\delta^2(u \cdot v) / (u \cdot v)^2 = \delta_u^2 / u^2 \pm 2\delta_{uv}^2 / uv + \delta_v^2 / v^2$ and $\delta^2(u \cdot v, u/v) = \delta_u^2 / u^2 \delta_v^2 / v^2$ directly, and by combining 1 and 2. Note: $\sqrt{\ldots \pm}$ is either $\cdots +$ or $/\ldots -$. (*hint: keep all errors relative*)

c) Apply this formula to the polarization P, where the two particle counts N_{\pm} obey Poisson statistics: $\delta^2 N_{\pm} = N_{\pm}$, and are uncorrelated: $\delta^2 N_{+-} = 0$. Show that $N_{\pm} = \frac{1}{2}N(1 \pm P)$ and use these to express δP in terms of N and P.

2. If individual measurements $x_i \pm \delta x_i$ have different uncertainties δx_i , they should be combined using the weighted average $x = \sum_i w_i x_i / \sum_i w_i$ instead of the normal mean to emphasize the best data points, i.e. the ones with the smallest errors.

a) Calculate δx , assuming the weights have no error. Following Bevington, show that the weights w_i which minimize the combined error δx are proportional to $w_i = \delta^{-2} x_i$, and the proportionality constant cancels in the weighted average. How does the combined error relate to χ^2 ?

b) [bonus: Likewise, show that the median $x_{1/2}$ minimizes the unweighted absolute deviation $\alpha(m) = \sum_i |x_i - m|$. This is slightly different than Bevington's definition using the mean \bar{x} , but shows the connection between the median and absolute deviation. It also shows that the median is a robust estimator of central tendency because it minimizes a lower-order moment, and thus is less sensitive to outliers. The mode is the most robust of all, being completely unaffected by outliers as long as their frequency is less than that of the peak.]

c) Show for counts N_i obeying Poisson statistics: $\delta^2 N_i = N_i$, the sum $N = \sum_i N_i$ has variance $\delta^2 N = N$, which also obeys Poisson statistics.

d) Given *n* measurements of polarization $P_i = \frac{N_i^+ - N_i^-}{N_i^+ + N_i^-} \ll 1$, from individual counts N_i^{\pm} , each with $\delta^2 P_i$ from question 1c), show that optimal weight is $w_i = N_i$ and thus $P = \sum_i w_i P_i / \sum_i w_i = \frac{N^+ - N^-}{N^+ + N^-}$, where $N^{\pm} = \sum_i N_i^{\pm}$ is the sum of the total counts in each state. Thus it does not matter how you bin individual runs before calculating the total polarization.