

Section 1.2 - Differential Calculus

* differential operator

~ ex. $u = x^2 \quad du = dx^2 = 2x dx$

$$d \equiv \lim_{\Delta \rightarrow 0} \Delta \approx 0$$

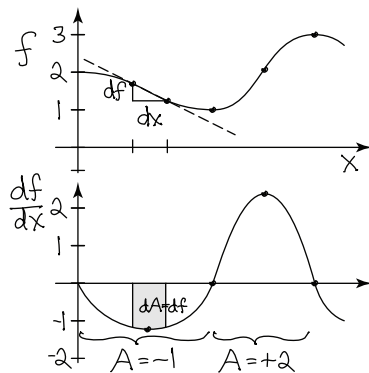
or $d(\sin x^2) = \cos(x^2) dx^2 = \cos x^2 \cdot 2x \cdot dx$

~ df and dx connected - refer to the same two endpoints

~ made finite by taking ratios (derivative or chain rule)

or infinite sum = integral (Fundamental Theorem of calculus)

$$\frac{df}{dx} = \frac{df}{du} \frac{du}{dx} \quad \int_a^b \frac{df}{dx} dx = \int_a^b df = f \Big|_a^b$$



* scalar and vector fields - functions of position ($\vec{r}$)

~ "field of corn" has a corn stalk at each point in the field

~ scalar fields represented by level curves (2d) or surfaces (3d)

~ vector fields represented by arrows, field lines, or equipotentials

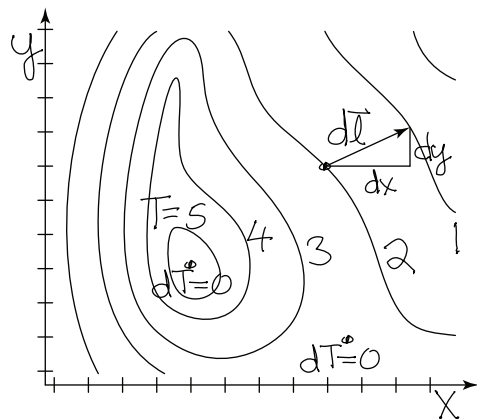
* partial derivative & chain rule

~ signifies one varying variable AND other fixed variables

~ notation determined by denominator; numerator along for the ride

~ total variation split into sum of variations in each direction

$$\frac{\partial u}{\partial x} \left(\frac{\partial u}{\partial x} \right)_{y,z} \frac{\partial u}{\partial x} u_{,x} \quad \dots = \frac{dx}{\dots} \frac{\dots}{\partial x} + \frac{dy}{\dots} \frac{\dots}{\partial y} + \frac{dz}{\dots} \frac{\dots}{\partial z}$$



* vector differential - gradient

~ differential operator, del operator

$$\begin{aligned} dT &= \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz \\ &= \underbrace{(\partial_x, \partial_y, \partial_z)}_{\vec{\nabla}} T \cdot \underbrace{(dx, dy, dz)}_{d\vec{l}} \end{aligned}$$

$$\begin{aligned} d &= dx \frac{\partial}{\partial x} + dy \frac{\partial}{\partial y} + dz \frac{\partial}{\partial z} = d\vec{r} \cdot \vec{\nabla} \\ \vec{\nabla} &= \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} = \frac{d}{d\vec{r}} \\ d\vec{l} &= \hat{x} dx + \hat{y} dy + \hat{z} dz = d\vec{r} \end{aligned}$$

~ differential line element: $d\vec{l}$ and $\frac{d\vec{l}}{dl}$ transforms between $\hat{x}, \hat{y}, \hat{z} \leftrightarrow dx, dy, dz$ and $d \leftrightarrow \vec{\nabla}$

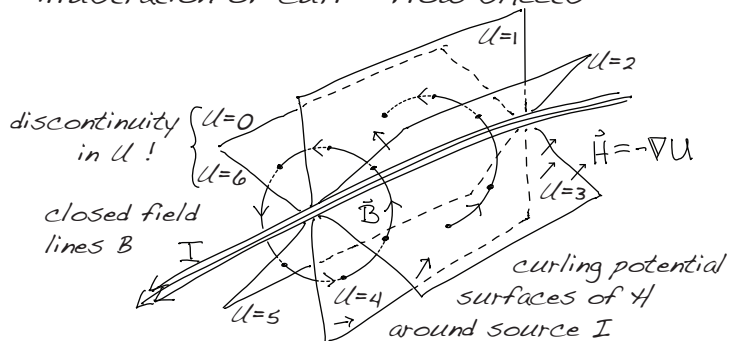
~ example: $d(x^2 y) = 2xy dx + x^2 dy = (2xy, x^2) \cdot (dx, dy)$

~ example: let $z = f(x, y)$ be the graph of a surface. What direction does $\vec{\nabla} f$ point?

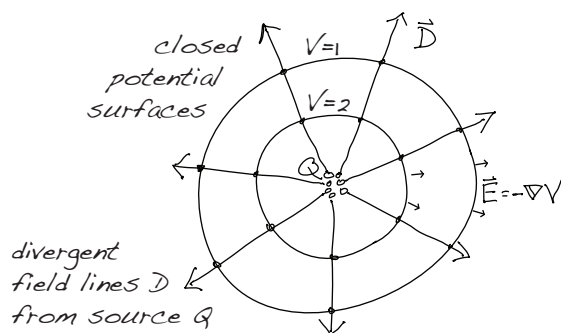
now let $g = z - f(x, y)$ so that $g = 0$ on the surface of the graph

then $\vec{\nabla} g = (-f_x, -f_y, 1)$ is normal to the surface

* illustration of curl - flow sheets



* illustration of divergence - flux tubes



Higher Dimensional Derivatives

- * curl - circular flow of a vector field

$$\nabla \times \vec{V} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \partial_x & \partial_y & \partial_z \\ V_x & V_y & V_z \end{vmatrix} = \begin{matrix} \hat{x} (V_{z,y} - V_{y,z}) \\ + \hat{y} (V_{x,z} - V_{z,x}) \\ + \hat{z} (V_{y,x} - V_{x,y}) \end{matrix}$$

* divergence - radial flow of a vector field

$$\nabla \cdot \vec{V} = (\partial_x \partial_y \partial_z) \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix} = V_{x,x} + V_{y,y} + V_{z,z}$$

* product rules

~ how many are there?

~ examples of proofs

$$\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$$

$$\vec{A} \times (\nabla \times \vec{B}) = \nabla (\vec{A} \cdot \vec{B}) - \vec{B} (\vec{A} \cdot \nabla)$$

$$\nabla \times (\vec{A} \times \vec{B}) = \vec{A}(\nabla \cdot \vec{B}) - \vec{B}(\nabla \cdot \vec{A})$$

$$\nabla(fg) = \nabla f \cdot g + f \cdot \nabla g$$

$$\nabla(\vec{A} \cdot \vec{B}) = \vec{A} \times (\nabla \times \vec{B}) + (\vec{A} \cdot \nabla) \vec{B} + (\vec{B} \cdot \nabla) \vec{A}$$

$$\nabla \times (f\vec{A}) = \nabla f \times \vec{A} + f(\nabla \times \vec{A})$$

$$\nabla \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} - \vec{B} (\nabla \cdot \vec{A}) - (\vec{B} \leftrightarrow \vec{A})$$

$$\nabla \cdot (f \vec{A}) = \nabla f \cdot \vec{A} + f \nabla \cdot \vec{A}$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = (\nabla \times \vec{A}) \cdot \vec{B} - \vec{A} \cdot (\nabla \times \vec{B})$$

* second derivatives - there is really only ONE! (the Laplacian)

$$\nabla^2 \equiv \nabla \cdot \nabla \equiv \partial_x^2 + \partial_y^2 + \partial_z^2$$

1) $\nabla \cdot (\nabla T) = \nabla^2 T$ ~ eg: $\nabla^2 T = 0$ no net curvature - stretched elastic band

$$(\nabla \cdot \nabla) \vec{v} = \nabla^2 \vec{v} \quad \sim \text{defined component-wise on } v_x, v_y, v_z \text{ (only cartesian coords)}$$

3), 5) $\nabla^2 = \nabla_{||}^2 + \nabla_{\perp}^2$ $\sim$ longitudinal / transverse projections $\nabla(\nabla \cdot \vec{v}) \equiv \nabla_{||}^2 \vec{v}$

$$= \nabla(\nabla \cdot \vec{v}) - \nabla \times \nabla \times \vec{v} \quad \vec{k} \cdot \vec{k} = \vec{k} \cdot \vec{k} = k^2 \quad -\nabla \times \nabla \times \vec{v} = -\nabla^2 \vec{v}$$

$$2), 4) \quad \nabla \times \nabla = 0 \quad \nabla \times (\nabla T) = 0 \quad \nabla \cdot (\nabla \times \vec{v}) = 0 \quad \nabla \times \nabla = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \partial_x & \partial_y & \partial_z \\ \partial_x & \partial_y & \partial_z \end{vmatrix} = \begin{vmatrix} \partial_y \partial_z - \partial_z \partial_y & \partial_z \partial_x - \partial_x \partial_z & \partial_x \partial_y - \partial_y \partial_x \end{vmatrix} = \begin{vmatrix} 0 & 0 & 0 \end{vmatrix} = 0$$

- * unified approach to all higher-order derivatives with differential operator

1) $dx^2 = 0$ 2) $dx^2 = 0$ 3) $dx dy = -dy dx$ + differential (line, area, volume) elements

$\sim$ Gradient

$$df = f_{,x} dx + f_{,y} dy + f_{,z} dz = \nabla f \cdot d\vec{l} \quad d\vec{l} = (dx, dy, dz) = d\vec{r}$$

 $\sim \text{curl}$

$$\begin{aligned} d(\vec{A} \cdot d\vec{l}) &= d(A_x dx + A_y dy + A_z dz) \\ &= A_{x,x} dx dx + A_{x,y} dy dx + A_{x,z} dz dx \\ &\quad + A_{y,x} dx dy + A_{y,y} dy dy + A_{y,z} dz dy \\ &\quad + A_{z,x} dx dz + A_{z,y} dy dz + A_{z,z} dz dz \\ &= (A_{z,y} - A_{y,z}) dy dz + (A_{x,z} - A_{z,x}) dz dx + (A_{y,x} - A_{x,y}) dx dy \end{aligned}$$

$$d(\vec{A} \cdot d\vec{a}) = (\nabla \times \vec{A}) \cdot d\vec{a}$$

$$d\vec{a} = (dydz, dzdx, dxdy) = \frac{1}{2} d\vec{l} \times d\vec{l} = d^2\vec{r}$$

~ Divergence

$$\begin{aligned} d(\vec{B} \cdot d\vec{a}) &= d(B_x dy dz + B_y dz dx + B_z dx dy) \\ &= B_{x,x} dx dy dz + B_{x,y} dy dy dz + B_{x,z} dz dy dz \\ &\quad + B_{y,x} dx dz dx + B_{y,y} dy dz dx + B_{y,z} dz dz dx \\ &\quad + B_{z,x} dx dx dy + B_{z,y} dy dx dy + B_{z,z} dz dx dy \\ &= (B_{x,x} + B_{y,y} + B_{z,z}) dx dy dz \end{aligned}$$

$$d(\vec{B} \cdot d\vec{a}) = \nabla \cdot \vec{B} \, d\tau \quad d\tau = \frac{1}{6} d\vec{l} \cdot d\vec{l} \times d\vec{l} = d^3\vec{r}$$

$$\nabla f = \frac{df}{dx} = \frac{df}{dr}$$

$$\nabla \times \vec{A} = \frac{d(\vec{A} \cdot d\vec{l})}{d\vec{a}} = \frac{d(d\vec{r} \cdot \vec{A})}{d^2\vec{r}}$$

$$\nabla \cdot \vec{B} = \frac{d(\vec{B} \cdot d\vec{a})}{d\tau} = \frac{d(d^2\vec{r} \cdot \vec{B})}{d^3\vec{r}}$$