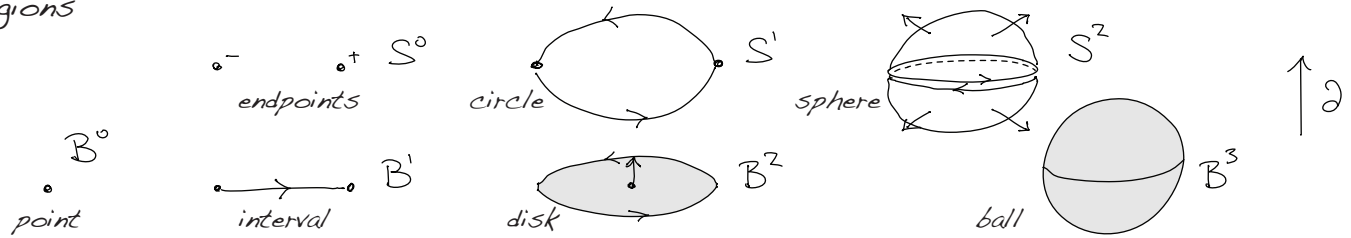


Section 1.3.2-5 - Region 1 Form = Integral

* Regions



~ definition of boundary operator ' ∂ '

'closed' region (cycle): $\partial S = 0$

~ a boundary is always closed $\partial \partial R = 0$

~ is every closed region a boundary?

$$\partial S = 0 \iff S = \partial R$$

~ a room (walls, window, ceiling, floor) is CLOSED if all doors, windows closed
is OPEN if the door or window is open;

~ what is the boundary?

~ think of a surface that has loops that do NOT wrap around disks!

* Forms - see last notes

~ combinations of scalar/vector fields and differentials so they can be integrated

~ pictorial representation enables 'integration by eye'

RANK	NOTATION	REGION	VISUAL REP.	DERIVATIVE
scalar	$\omega^{(0)} = f$	$\partial \rightarrow Q$ point	level surfaces	$d\omega^{(0)} = \nabla f \cdot d\vec{l}$
vector	$\omega^{(1)} = \vec{A} = \vec{A} \cdot d\vec{l}$	$\partial \rightarrow P$ path	flow sheets	$d\omega^{(1)} = \nabla \times \vec{A} \cdot d\vec{a}$
p-vector	$\omega^{(2)} = \vec{B} = \vec{B} \cdot d\vec{a}$	$\partial \rightarrow S$ surface	flux tubes	$d\omega^{(2)} = \nabla \cdot \vec{B} d\tau$
p-scalar	$\omega^{(3)} = \tilde{\rho} = \rho d\tau$	$\partial \rightarrow V$ volume	subst boxes	$d\omega^{(3)} = 0$

edge of the world!

~ properties of differential operator ' d '

transforms form into higher-dimensional form, sitting on the boundary

~ Poincare lemma

$$d\omega = 0$$

$$\nabla \times \nabla V = 0$$

$$\nabla \cdot \nabla \times \vec{A} = 0$$

~ converse - existence of potentials $V, \vec{A}$

$$d\omega = 0 \iff \omega = d\alpha$$

$$\nabla \times \vec{E} = 0 \iff \vec{E} = -\nabla V$$

$$\nabla \cdot \vec{B} = 0 \iff \vec{B} = \nabla \times \vec{A}$$

for space without any n-dim 'holes' in it

* Integrals - the overlap of a region on a form = integral of form over region

~ regions and forms are dual - they combine to form a scalar

~ generalized Stoke's theorem:

' ∂ ' and ' d ' are adjoint operators - they have the same effect in the integral

$$\int_R d\omega = \int_{\partial R} \omega$$

$$\text{note: } 0 = \int_{\partial R} \omega = \int_{\partial R} d\omega = \int_R dd\omega = 0$$

Generalized Stokes Theorem

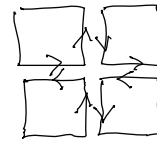
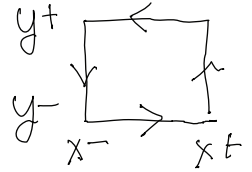
* Fundamental Theorem of Vector Calculus: 0d-1d

$$\int_a^b \nabla \varphi \cdot d\vec{l} = \int_a^b df = f(b) - f(a)$$

$$\begin{matrix} d\vec{l} \\ df + df + df + df \\ f=0 \quad 1 \quad 2 \quad 3 \end{matrix} = \Delta f$$

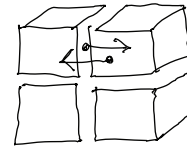
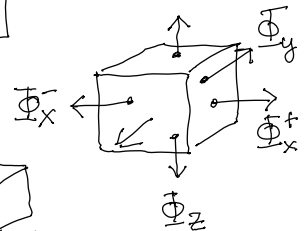
* Stokes' Theorem: 1d-2d

$$\begin{aligned} \nabla \times \vec{A} \cdot d\vec{a} &= \frac{\partial A_y}{\partial x} dx dy - \frac{\partial A_x}{\partial y} dx dy + \dots \\ &= A_y(x^+) dy + A_y(x^-)(-dy) + A_x(y^+)(-dx) + A_x(y^-) dx + \dots \\ &= \sum \vec{A} \cdot d\vec{l} \text{ around boundary} \\ &\quad + \text{other faces} \end{aligned}$$



* Gauss' Theorem: 2d-3d (divergence theorem)

$$\begin{aligned} \nabla \cdot \vec{B} d\tau &= \frac{\partial B_x}{\partial x} dx dy dz + \frac{\partial B_y}{\partial y} dy dz dx + \frac{\partial B_z}{\partial z} dz dx dy \\ &= B_x(x^+) dy dz + B_x(x^-)(-dy dz) + 4 \text{ other faces} \\ &= \sum \vec{B} \cdot d\vec{a} \text{ around boundary} \end{aligned}$$



* note: all interior $f(x)$, flow, and flux cancel at opposite edges

* proof of converse Poincare lemma: integrate form out to boundary

* proof of gen. Stokes theorem: integrate derivative out to the boundary

$$\int_R d\omega = \oint_{\partial R} \omega \iff \int_P \nabla \varphi \cdot d\vec{l} = \oint_{\partial P} \varphi \quad \int_S \nabla \vec{A} \cdot d\vec{a} = \oint_{\partial S} \vec{A} \cdot d\vec{l} \quad \int_V \nabla \cdot \vec{B} d\tau = \oint_{\partial V} \vec{B} \cdot d\vec{a}$$

* example - integration by parts

$$\nabla \cdot \left(\frac{\hat{r}}{r^2} f \right) = \left(\nabla \cdot \frac{\hat{r}}{r^2} \right) f + \frac{\hat{r}}{r^2} \cdot \nabla f$$

$$\int_V \frac{\hat{r}}{r^2} \cdot \nabla f d\tau = \int_V \nabla \cdot \left(\frac{\hat{r}}{r^2} f \right) d\tau - \int_V \left(\nabla \cdot \frac{\hat{r}}{r^2} \right) f d\tau$$

$$\int_V \frac{1}{r^2} \frac{\partial f}{\partial r} r^2 dr \cdot d\Omega = \oint_{\partial V} d\vec{a} \cdot \frac{\hat{r}}{r^2} f - \int_V 4\pi \delta^3(\vec{r}) f d\tau$$

$$\int d\Omega \int_{r=0}^R df = \int r^2 d\Omega \hat{r} \cdot \frac{\hat{r}}{r^2} f - 4\pi f(0)$$

$$\int d\Omega f(R) - f(0) = \int d\Omega f(R, \theta, \phi) - 4\pi f(0)$$

$$4\pi [\langle f \rangle_R - f(0)] = 4\pi [\langle f \rangle_R - f(0)]$$