Review of Electrostatics (Chapters 1-4)

 $\vec{X} = \vec{b}_i \, \chi^i \equiv \sum_{i=1}^3 \vec{b}_i \, \chi^i$

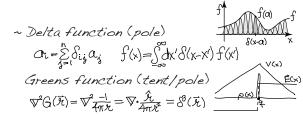
STOKES

THEOREM

* Chapter 1: Mathematics - Vector Calculus

- ~ Vectors (it's all about being Linear!)
 linear combinations; projections
 basis (independence, closure)
- ~ Metric & Cross Product (Bilinear)
 orthonormal basis \(\hat{\hat{n}} \hat{\hat{n}} \hat{\hat{n}} \hat{\hat{n}} \hat{\hat{n}} \tag{\kappa}
 longitudinal / transverse projections
- ~ Linear Operators
 eigenstuff: rotations / stretches
- ~ Function Spaces continuous vs discrete Sturm-Liouville (orthogonal eigenfunctions)
- ~ Vector Derivatives and Integrals (linearization) Differentials ordered naturally by dimension

RANK	REGION	INTEGRAL
scalar	Q point	$\Delta f = f _a^b$ change
vector	REGION Of Point Of Poth	Ex=9, A.d flow
p-vector	S surface	Φ8=98β·dà f/ux
p-scalar	S surface	Q=Spdr subst.



- ~ Helmholtz theorem: source and potential

$$\vec{F} = -\nabla\left(-\nabla^{2}\nabla\cdot\vec{F}\right) + \nabla \times\left(-\nabla^{2}\nabla\cdot\vec{F}\right)$$

$$= -\nabla V + \nabla \times\vec{A} \quad \nabla^{2}(V,\vec{A}) = -(\rho,\vec{J}) \quad \nabla \cdot\vec{F} = \rho$$

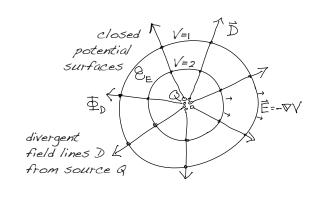
$$\nabla \cdot\vec{F} = \rho$$

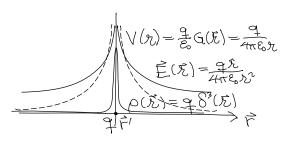
DERIVATIVE	GEOMETRY
df × da = V.A.da × da = V.B.da	level surface
dA.di Dt.dl	flow sheets
dB. da VxA. da	flux tubes d
× ~ D.Bdc	level surface d flow sheets d flux tubes d subst boxes d

* Chapter 2: Formulations of Electrostatics

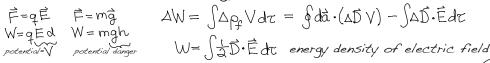
Integral	Differential	Boundary
$\vec{E} = \int \frac{dq' \hat{r}}{4\pi \epsilon r^2}$	$\nabla^2 \vec{E} = \nabla p_{\mathcal{E}}$	dq=oda
& _e =0 Φ _p =Q	$\nabla \times \vec{E} = 0$ $\nabla \cdot \vec{D} = \rho$	$\Delta \hat{N} \times \vec{E} = \vec{E}_{t} - \vec{E}_{t} = 0$ $\Delta \hat{N} \cdot \vec{D} = \vec{D}_{2n} - \vec{D}_{1n} = \vec{O}_{f}$
V=-JĒ·dĪ V= Jād Trēst	$ \vec{E} = -\nabla V $ $ \vec{E} = -\nabla V $ $ \vec{E} = -\nabla V $	$ \begin{aligned} &\bigvee_{2} - \bigvee_{1} = O \\ &- \varepsilon_{2} \partial_{n} \bigvee_{2} + \varepsilon_{1} \partial_{n} \bigvee_{1} = \sigma_{f} \end{aligned} $
Relation between	V <u>−∇V</u>	Ē <u>₹**</u> ₽

Relation between potential, field, and source:





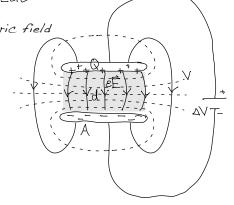
~ Work and Electric field energy: flux x flow



~ Conductors and Capacitance: flux / flowp=E=0, V=const inside; D=T, V laminar outside conductor

$$C = \frac{Q}{\Delta V} = \frac{\Phi_{D}}{E_{E}} \qquad Q = \int d\vec{\alpha} \cdot \vec{D} = \Phi_{D} \quad (closed surface)$$

$$= \underbrace{E\Phi_{E}}_{E_{E}} \approx \underbrace{EA}_{d} \qquad W = \int d\vec{l} \cdot \vec{E} = E_{E} \quad (open path)$$



- * Chapter 3: Solutions of LaPlace Equation
 - ~ Uniqueness Theorem for exterior boundary conditions

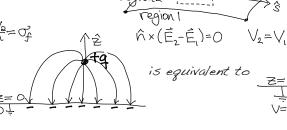
$$O = \int_{\partial V} \frac{\partial u}{\partial x} = \int_{\partial V} \frac{\partial u}{\partial x} = \int_{\partial V} \frac{\partial u}{\partial x} \cdot (u \nabla u) = \int_{\partial V} \nabla \cdot (u \nabla u) d\tau = \int_{\partial V} u \nabla^2 u + |\nabla u|^2 d\tau$$

a) Dirichlet B.C. specifies potential on boundary; b) Neuman B.C. specifies flux on boundary

~ continuity boundary conditions stitch potentials together in adjacent regions

Flux: D= &E n A region 2

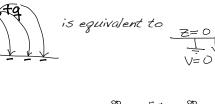
 $\hat{\mathbf{n}} \cdot (\hat{\mathbf{D}}_1 - \hat{\mathbf{D}}_1) = \mathbf{\sigma} - \mathbf{\epsilon}_1 \frac{8V_2}{3n} + \mathbf{e}_1 \frac{3V_2}{3n} = \mathbf{\sigma}_1^2$



- A) METHOD OF IMAGES find a point charge distribution with the same B.C.'s same solution by uniques theorem
- B) METHOD OF SEPARATION OF VARIABLES separate Laplacian (10 known coordinate systems) solve Sturm-Louiville ODE in each dimension match boundary conditions to find coefficients Fourier trick: orthogonal basis functions
- C) METHOD OF MULTIPOLE MOMENTS series expansion of potential about origin or infinity

$$\sqrt{(\vec{r})} = \frac{1}{4\pi\epsilon_0 r^2} \int d\vec{q} \ r'\cos\theta = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3} \qquad \vec{p} = \int d\vec{q}' \vec{r}'$$

$$\frac{1}{4\pi \varepsilon_0 r^5} \qquad \frac{1}{2\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} = \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} = \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} = \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0 r^4} = \frac{1}{3\pi \varepsilon_0 r^4} \frac{1}{3\pi \varepsilon_0$$



$$V(x,y) = \sum_{n=1}^{\infty} C_n e^{\vec{k} \cdot \vec{r}} = \sum_{n=1}^{\infty} C_n e^{-k_n x} \sin(k_n y)$$

$$\phi(x) = \sin(k_n x) \quad V(x) = \sum_{n=1}^{\infty} c_n \phi_n(x)$$

$$\langle \phi_n | \phi_m \rangle = \int_0^a \sin(k_n x) \cdot \sin(k_n x) dx = \frac{a}{a} \delta_{nm}$$

$$C_{m} = \langle \phi_{m}(x) | V(x) \rangle / \frac{a}{a}$$

$$V(r, 0) = \sum_{l=0}^{\infty} \left(A_{l} r^{l} + \frac{B_{l}}{r^{l+1}} \right) P_{l}(\cos \theta)$$

* Chapter 4: Dielectric Materials - Dipole N= PXE U=-P.E P=V(P.E)

$$\vec{N} = \vec{p} \times \vec{E}$$
 $U = -\vec{p} \cdot \vec{E}$ $\vec{F} = \nabla(\vec{p} \cdot \vec{E})$

$$\vec{P} = \vec{\alpha} \cdot \vec{E} \qquad \mathcal{E}_{o} \cdot \vec{\chi}_{e} \cong \vec{N} \times \vec{E}$$

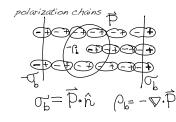
$$\vec{P} = \vec{e}_{o} \cdot \vec{\chi}_{e} \vec{E} = \frac{\vec{\Delta} \vec{P}}{\vec{\Delta} \vec{C}} = \frac{\vec{\Delta} \vec{N}}{\vec{\Delta} \vec{C}} \vec{P} = \vec{N} \times \vec{E}$$

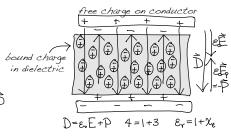
$$\vec{D} = \vec{e}_{o} \cdot \vec{E} + \vec{P} = \vec{e}_{o} \cdot (\vec{I} + \vec{\chi}_{e}) \vec{E} = \vec{e}_{e} \cdot \vec{E} \times \vec{E} = \vec{e}_{e} \cdot \vec{E}$$

$$\vec{E}_{r} = \vec{I} + \vec{\chi}_{e} = \vec{e}_{e} \cdot \vec{E}$$

$$\vec{E}_{r} = \vec{I} + \vec{\chi}_{e} = \vec{e}_{e} \cdot \vec{E}$$

$$\vec{E}_{r} = \vec{P} \cdot \hat{\vec{N}} \cdot \vec{P} = \vec{P} \cdot \vec{P} \cdot \vec{P} \cdot \vec{P} \cdot \vec{P} \cdot \vec{P} = \vec{P} \cdot \vec{P} \cdot$$





* Outlook - road to electrodynamic equations

$$\begin{split} & \underline{\Phi}_D = Q_{end} & \underline{\Phi}_B = Q & -\underline{Q}^2(V_j \overrightarrow{A}) = (\beta_{E_j} \mu \overrightarrow{J}) \\ & \underline{\mathcal{E}}_B = -\frac{\partial \underline{\Phi}_B}{\partial t} & \underline{\mathcal{E}}_H = \underline{I}_{end} + \frac{\partial \underline{\Phi}_D}{\partial t} & (wave equation) \end{split}$$

 $\vec{F} = q(\vec{E} + \vec{\nabla} \times \vec{B}) = (\rho \vec{E} + \vec{J} \times \vec{B}) dr$ 2p+ V-J=0 V.D=p VxE+2B=0 $\nabla \cdot \vec{B} = 0$ $\nabla x \vec{h} - \partial_t \vec{D} = \vec{J}$ D= EĒ J= dĒ B= MĀ Ē=-VV-2Ā B= VxA

 $V \rightarrow V - \partial_{+} \lambda$ $A \rightarrow A + \nabla \lambda$

Lorentz force Continuity Maxwell electric, magnetic fields Constitution Potentials Gauge transform