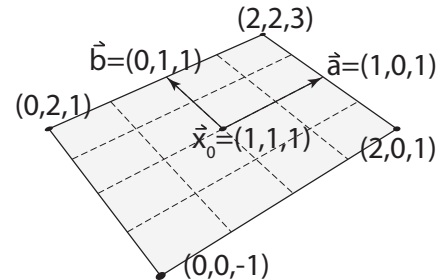


University of Kentucky, Physics 416G
Problem Set #3, Rev. B, due Friday, 2014-09-26

1. a) Plot a 2-D graph of the function $h(x, y) = 2xy$ by drawing level curves in the xy -plane.
- b) Plot a 3-D graph of the 2-D function $h(x, y)$, ie. the surface $\{(x, y, z) \mid z = h(x, y)\}$.
- c) Calculate the gradient of h at all points, and also the divergence and curl of the gradient. Plot the field lines and equipotentials of the gradient. Note that the equipotentials are curves, not surfaces, since $h(x, y)$ is 2-dimensional. Bonus: Calculate an equation for field line curves.
- d) Construct a 3-D function $g(x, y, z)$ which has $z = h(x, y)$ as one level surface. Calculate the gradient of this function to obtain a normal vector to the surface $z = h(x, y)$ at all points on the surface. Compare your answer to the normal of the surface calculated using the cross product (hint: calculate $\mathbf{da}$ on the surface).
- e) Show that there is a linear coordinate transformation $(x, y) \rightarrow (x', y')$ that transforms the function $h'(x', y') = y'^2 - x'^2$ into $h(x, y)$. We will find that both of these functions are $m = 2$ cylindrical harmonics.
- f) Show that $h_1(x, y) = 2xy$ and $h_2(x, y) = y^2 - x^2$ form a basis for all functions which can be generated from h_1 and h_2 by rotating the coordinates (x, y) by an angle θ via the transformation $\mathbf{r}' = R_\theta \mathbf{r}$, i.e. $\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} c_\phi & -s_\phi \\ s_\phi & c_\phi \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$, where $c_\phi = \cos \phi$ and $s_\phi = \sin \phi$.
- g) Verify Stokes' theorem $\oint_{\partial R} \mathbf{v} \cdot d\mathbf{l} = \int_R \nabla \times \mathbf{v} \cdot d\mathbf{a}$ using the vector field $\mathbf{v}(x, y, z) = \hat{x}yz$ over the surface $z = h_1(x, y)$, where $x^2 + y^2 < 1$.

2. a) Integrate $\int_S \mathbf{v} \cdot d\mathbf{a}$ where $\mathbf{v} = \hat{x}x^2 + \hat{y}2yz + \hat{z}xy$, and S is the parallelogram in the figure to the right. Hint: remember the parameterization of HW1 #1.



- b) Integrate $\oint_{\partial S} \mathbf{v} \cdot d\mathbf{l}$ along the boundary of S .
- c) Verify Stokes' theorem for the integral in part b.

2' [alternate or bonus] Fundamental Theorem of Differentials: In class we discussed an extension of the Fundamental Theorem of Calculus in higher dimensions: $d \int_n \omega + \int_n d\omega = \omega$, where n is a 'radial' coordinate, and $\int_n$ is an indefinite integral starting at $n = 0$. This theorem encompasses both the Poincaré lemmas (indefinite integral: potential theory), and the boundary theorems (definite integral: gradient, curl, divergence theorems).

- a) Show that this theorem reduces to the FTC for both functions $f(x)$ and distributions $\rho(x)dx$ in one dimension. What happens to the constant of integration for indefinite integrals?
- b) Apply this theorem to calculate the potential V of an conservative field $\mathbf{E}$, ie. $\mathbf{E} = -\nabla V$ when $\nabla \times \mathbf{E} = \mathbf{0}$. How does this relate to Stokes' theorem?
- c) Apply this theorem to calculate the potential $\mathbf{A}$ of a solenoidal field $\mathbf{B}$, ie. $\mathbf{B} = \nabla \times \mathbf{A}$ when $\nabla \cdot \mathbf{B} = 0$. Compare your answer with Griffiths 3ed[4ed] problem 5.51[53]. How does this relate [if at all] to Gauss' theorem?

Also, Griffiths 3ed[4ed] Ch. 1, #35[36], 44[45], 45[46], 46[47], 47[48], 48[49], 60[61], 61[62].