

Section 3.1 - Laplace's Equation

- * overview: we leared the math (Ch 1) and the physics (Ch 2) of electrostatics basically concepts of Phy 232 described in a new sophisticated language
 - ~ Ch 3: Boundary Value Problems (BVP) with Laplace's equation (NEW!)
 - a) method of images b) separation of variables c) multipole expansion
 - ~ Ch 4: Dielectric Materials: free and bound charge (more in-depth than Phy 232)

$$\chi \xrightarrow{d} (V, \vec{A}) \xrightarrow{d} (\vec{E}, \vec{B}) \xrightarrow{d} 0$$

(I) Brute force!

$$\vec{E} = \int \frac{dq \hat{r}}{4\pi\epsilon_0 r^2}$$

(II) Symmetry

$$\begin{aligned} \Phi_D &= Q \\ \vec{E}_E &= 0 \end{aligned}$$

(IV) Refined brute

$$V = \int \frac{dq}{4\pi\epsilon_0 r}$$

$$\begin{aligned} \epsilon \parallel \mu & \leftarrow \vec{S} \\ (\vec{D}, \vec{H}) & \xrightarrow{d} (\rho, \vec{J}) \xrightarrow{d} 0 \end{aligned}$$

(III) Elegant but cumbersome

$$\begin{aligned} \nabla \cdot \vec{D} &= \rho \\ \nabla \times \vec{E} &= 0 \end{aligned} \quad \text{Ch. 4}$$

(V) the WORKHORSE !!

$$-\nabla^2 V = \rho/\epsilon \quad \text{Ch. 3}$$

Equations of electrodynamics:

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

Lorentz force

$$\nabla \cdot \vec{J} + \partial_t \rho = 0$$

Continuity

$$\nabla \cdot \vec{D} = \rho \quad \nabla \times \vec{E} + \partial_t \vec{B} = 0$$

Maxwell electric,

$$\nabla \cdot \vec{B} = 0 \quad \nabla \times \vec{H} - \partial_t \vec{D} = \vec{J}$$

magnetic fields

$$\vec{D} = \epsilon \vec{E} \quad \vec{B} = \mu \vec{H} \quad \vec{J} = \sigma \vec{E}$$

Constitution

$$\vec{E} = -\nabla V - \partial_t \vec{A} \quad \vec{B} = \nabla \times \vec{A}$$

Potentials

$$V \rightarrow V - \partial_t \lambda \quad \vec{A} \rightarrow \vec{A} + \nabla \lambda \quad \text{Gauge transform}$$

* Classical field equations - many equations, same solution:

Laplace/Poisson: $\nabla^2 V = 0$ $-\nabla \cdot \epsilon \nabla V = \rho$ ~ potentials (V, \vec{A}) , dielectric ϵ , permeability μ

Maxwell wave: $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} (V, \vec{A}) - \nabla^2 (V, \vec{A}) = \mu(\rho, \vec{J})$ ~ speed of light $c = \frac{1}{\sqrt{\epsilon\mu}}$, charge/current density (ρ, \vec{J})

Heat equation: $C \frac{\partial T}{\partial t} = k \nabla^2 T$ ~ temp T , cond. k , heat $\vec{q} = -k \nabla u$, heat cap. C

Diffusion eq: $\frac{\partial u}{\partial t} = D \nabla^2 u$ ~ concentration u , diffusion D , flow $D \nabla u$

Drumhead wave: $\frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} - \nabla^2 u = f$ ~ displacement u , speed of sound c , force f

Schrödinger: $-\frac{\hbar^2}{2m} \nabla^2 \Psi + V\Psi = i\hbar \frac{\partial \Psi}{\partial t}$ ~ prob amp Ψ , mass m , potential V , Planck \hbar

* 1-dimensional Laplace equation $\nabla^2 V = \frac{\partial^2 V}{\partial x^2} = 0$

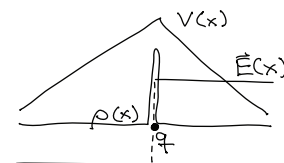
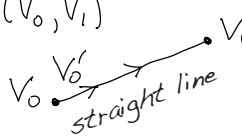
$$\frac{dV}{dx} = \int dx = a \quad V = \int dx = ax + b$$

~ charge singularity between two regions:

~ a, b satisfy boundary conditions (V_0, V_0') or (V_0, V_1)

~ mean field: $V(x) = \frac{1}{2}(V(x-a) + V(x+a))$

~ no local maxima or minima (stretches tight)



* 2-dimensional Laplace equation $\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} = 0$

~ no straightforward solution (method of solution depends on the boundary conditions)

~ Partial Differential Equation (elliptic 2nd order)

~ chicken & egg: can't solve $\frac{\partial^2 V}{\partial x^2}$ until you know $\frac{\partial^2 V}{\partial y^2}$

~ solution of a rubber sheet

~ no local extrema -- mean field:

$$V(\vec{r}) = \frac{1}{2\pi R} \oint_{\text{circle}} V dl$$

~ charge singularity between two regions:

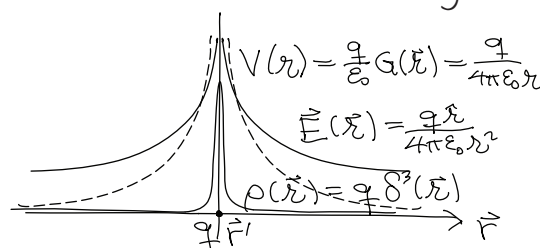
* 3-dimensional Laplace equation

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

~ generalization of 2-d case

~ same mean field theorem:

$$V(\vec{r}) = \frac{1}{4\pi R^2} \oint_{\text{sphere}} V da$$



Boundary Conditions

* 2nd order PDE's classified in analogy with conic sections: replacing $\frac{\partial}{\partial x}$ with x , etc

a) Elliptic - "spacelike" boundary everywhere (one condition on each boundary point)
eg. Laplace's eq, Poisson's eq. $\nabla^2 V = 0$ $-\nabla \cdot \epsilon \nabla V = \rho$

b) Hyperbolic - "timelike" (2 initial conditions) and "spacelike" parts of the boundary
eg. Wave equation $\frac{1}{c^2} \frac{\partial^2 (V, \vec{A})}{\partial t^2} - \nabla^2 (V, \vec{A}) = \mu(\rho, \vec{J})$

c) Parabolic - 1st order in time (1 initial condition)
eg. Heat equation, Diffusion equation $c \frac{\partial T}{\partial t} = k \nabla^2 T$ $\frac{\partial u}{\partial t} = D \nabla^2 u$

* Uniqueness of a BVP (boundary value problem) with Poisson's equation:

if V_1 and V_2 are both solutions of $\nabla^2 V = -\rho/\epsilon_0$ then let $U = V_1 - V_2$ $\nabla^2 U = 0$

integration by parts: $\nabla \cdot (U \nabla U) = U \nabla \cdot \nabla U + \nabla U \cdot \nabla U = U \nabla^2 U + (\nabla U)^2$

in region of interest: $\int_{\partial V} d\vec{a} \cdot (U \nabla U) = \int_V \nabla \cdot (U \nabla U) d\tau = \int_V U \nabla^2 U + (\nabla U)^2 d\tau$

note that: $\nabla^2 U = 0$ and $(\nabla U)^2 > 0$ always

thus if $\int_{\partial V} d\vec{a} \cdot U \nabla U = \int_{\partial V} d\vec{a} U \frac{\partial U}{\partial n} = 0$ then $\int_V (\nabla U)^2 d\tau = 0 \Rightarrow U = 0$ everywhere

a) Dirichlet boundary condition: $U = 0$ - specify potential $V_1 = V_2$ on boundary

b) Neuman boundary condition: $\frac{\partial U}{\partial n} = 0$ - specify flux $\frac{\partial V_1}{\partial n} = \frac{\partial V_2}{\partial n}$ on boundary

* Continuity boundary conditions - on the interface between two materials

Flux:

$\vec{D} \equiv \epsilon \vec{E}$
(shorthand for now)



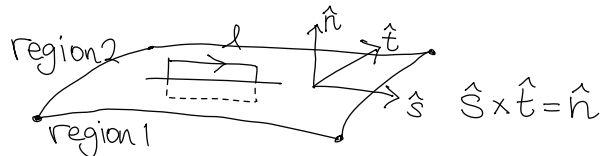
$$\Phi = \oint_{\partial V} \vec{D} \cdot d\vec{a} = \int_V \sigma da = Q$$

$$\hat{n} \cdot (\vec{D}_2 - \vec{D}_1) A = \sigma \cdot A$$

$$\hat{n} \cdot (\vec{D}_2 - \vec{D}_1) = \sigma$$

$$-\frac{\partial V_2}{\partial n} + \frac{\partial V_1}{\partial n} = \sigma/\epsilon_0$$

Flow:



$$\oint_{\partial S} \vec{E} \cdot d\vec{l} = \int_S \nabla \times \vec{E} \cdot d\vec{a}$$

$$\hat{s} \cdot (\vec{E}_2 - \vec{E}_1) l = \hat{t} \cdot \nabla \times \vec{E} l w = 0$$

$$\hat{n} \times (\vec{E}_2 - \vec{E}_1) = 0$$

$$V_2 = V_1$$

* the same results obtained by integrating field equations across the normal

$$\nabla \cdot \vec{D} = \rho/\epsilon_0$$

$$\nabla \times \vec{E} = \vec{K}_e \delta(n)$$

$$\nabla \times \vec{E} = \begin{vmatrix} \hat{s} & \hat{t} & \hat{n} \\ \partial_s & \partial_t & \partial_n \\ E_s & E_t & E_n \end{vmatrix}$$

$$\int_{-}^{+} dn \left(\frac{\partial D_n}{\partial n} + \frac{\partial D_s}{\partial s} + \frac{\partial D_t}{\partial t} \right) = \int_{-}^{+} dn \sigma \delta(n)$$

$$\int_{-}^{+} dn \left(\hat{t} \frac{\partial E_s}{\partial n} - \hat{s} \frac{\partial E_t}{\partial n} \right) = \int_{-}^{+} dn \vec{K}_e \delta(n)$$

$$\int dD_n = \hat{n} \cdot \Delta \vec{D} = \sigma$$

$$\hat{n} \times \Delta \vec{E} = \vec{K}_e = 0$$

~ opposite boundary conditions for magnetic fields: $\hat{n} \cdot \Delta \vec{B} = 0$ $\hat{n} \times \Delta \vec{H} = \vec{K}$