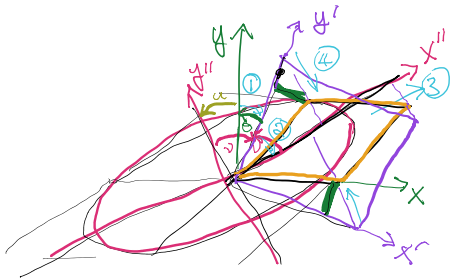
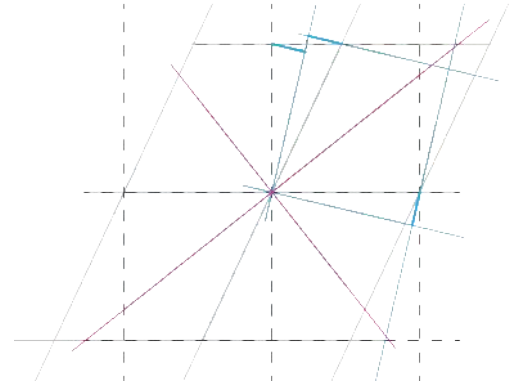


Characterization of Linear Operators

Sunday, October 4, 2015 8:44 AM

* Polar decomposition

- any matrix M can be expressed as a rotation R and stretch S



Rotation to sym. R ① $R = \begin{pmatrix} c_\theta & -s_\theta \\ s_\theta & c_\theta \end{pmatrix}$
 Eigenvector to ellipse V } $S = VWV^{-1}$
 Eigenval w } ② $V = \begin{pmatrix} c_\psi & -s_\psi \\ s_\psi & c_\psi \end{pmatrix}$
 ③ ④ $W = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$ } $M = \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix}$

- example: sheer transformation (see ppt)
 - the stretch $S = VWV^T$ is diagonal after further rotation
 - combine rotations: singular value decomposition (SVD)
- $M = RS = R(VWV^T) = U(WV^T)$ where $U^T U = I$ $V^T V = I$

* Diagonalization - notation of eigensystems

$$M \vec{u}_i = \lambda_i \vec{u}_i \quad U = \begin{pmatrix} u_1 & u_2 & u_3 \\ \downarrow & \downarrow & \downarrow \end{pmatrix} \quad D = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}$$

$$M U = U D$$

$$U^T M U = D \quad U^T U = I, \text{ otherwise } U^{-1} M U = D$$

similarity transform - change of basis (rotation)

$$M = U D U^T = \sum_i \lambda_i \underbrace{\vec{u}_i \vec{u}_i^T}_{\text{projector } P_i} \quad I = U U^T = (\vec{u}_1 \vec{u}_2 \dots) \begin{pmatrix} \vec{u}_1^T \\ \vec{u}_2^T \\ \vdots \end{pmatrix} = \sum_i \underbrace{\vec{u}_i \vec{u}_i^T}_{\text{projector } P_i}$$

* Exponential - Normal Matrix analogy.

- a square matrix G can be decomposed into symmetric T and antisymmetric A parts

$$\frac{1}{2}(M + M^T) \equiv T$$

$$\frac{1}{2}(M - M^T) \equiv A$$

$$M = T + A$$

with respect to the adjoint

- take the exponential of each:

$T^\dagger = T$	$A^\dagger = -A$
Hermitian	antiHermitial

$$T^\dagger = T \quad A^\dagger = -A$$

Hermitian anti Hermital

a) $T = VDV^T$
 $S \equiv e^T = Ve^D V^T$ because $T^T = T$
 semi positive definite: (+) eigenvalues

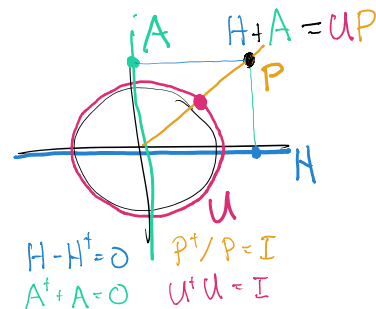
b) $R \equiv e^A$ $R^\dagger R = e^{-A} \cdot e^A = e^0 = I$ unitary
 $\text{Det } R = \text{Det } e^A = e^{\text{Tr } A} = |e^{i0}| = 1$

c) $M = e^G$ \leftarrow generator if $[T, A] = 0$ (M is normal), then
 $= e^{T+S} = e^T \cdot e^S = S \cdot R$ polar decomposition

— Summary:

complex analogy

$$\begin{aligned} \exp(G = T + A) &= (M = S \cdot R) \\ \exp(W = \tau + i\phi) &= (Z = s \cdot r) \quad s = e^\tau \quad r = e^{i\phi} \end{aligned}$$



a) Normal $N = H + iK$ $H^+ = H$ $K^+ = K$ $NN^+ = N^+N$ $HK = KH$ $\rightarrow n$ complex eigenvalues.

b) (anti) Hermitian $H^\dagger = H$ $A^\dagger = (iK)^\dagger = -iK = -A$
 \rightarrow (imaginary) real eigenvalues

c) Positive definite: positive eigenvalues

c) Unitary: $U^\dagger U = I$ unit eigenvalues. $e^{i\theta_i}$

- Proofs: if $f(x) = \sum_i a_i x^i$ and $M = UDU^T$ then

note $U \underbrace{DU^{-1}U}_{I}DU^{-1} = U D^2 U^{-1}$

$$\begin{aligned} f(M) &\equiv \sum_i a_i M^i = \sum_i a_i (U D U^\dagger)^i \\ &= U \left(\sum_i a_i D^i \right) U^\dagger \\ &= U \cdot \text{diag}(f(\lambda_i)) \cdot U^{-1} = U \begin{pmatrix} f(\lambda_1) & & \\ & f(\lambda_2) & \\ & & \ddots \end{pmatrix} U^{-1} \end{aligned}$$

$$e^{\text{Tr} M} = \exp(\text{Tr}(U^{-1} D U)) = U \exp(\text{Tr}(\tau_1 \tau_2 \dots)) U^{-1}$$

$$= U e^{\lambda_1 + \lambda_2 + \dots} U^{-1} = U \text{Det} e^D U^{-1} \\ = \det e^M$$

* Characterization of eigensystems:

- note (SVD): $M = UWV^T$ but can we say $M = UDU^{-1}$?

a) $\text{End}(n)$: any $n \times n$ matrix has n complex eigenvalues
however degenerate λ_i may not have same # of eigenvectors
defective eigenvalues \approx dilation + nilpotent parts of matrix

Example: Shear: $M = \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + a \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$

$$\begin{aligned} Z \begin{pmatrix} 1 \\ 0 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} & Z \vec{v}_0 &= 0 \vec{v}_0 & & = 1 I + a Z \\ Z \begin{pmatrix} 0 \\ 1 \end{pmatrix} &= \begin{pmatrix} 0 \\ 1 \end{pmatrix} & Z \vec{v}_1 &= \vec{v}_0 & \leftarrow & \text{Jordan chain of} \\ & & & & & \text{generalized eigenvectors.} \end{aligned}$$

Thus defective matrices still
admit Jordan decompositions
 $M = UJU^{-1}$

$$J = \begin{pmatrix} \lambda_1 & 1 & 0 & & \\ 0 & \lambda_1 & 1 & & \\ & & \lambda_1 & & \\ & & & \lambda_2 & \\ & & & & \lambda_2 \end{pmatrix} \begin{array}{l} \text{block diag} \\ \text{w/ superdiag.} \\ \text{1's.} \end{array}$$

b) Normal matrices $N^\dagger N = NN^\dagger$

equivalently $N = H + iK$ $H^\dagger = H$ $K^\dagger = K$ $[H, K] = 0$
 H and K each have real eigenvalues

since $[H, K] = 0$, there exist common eigenvectors

thus N has a set of "independent" complex

eigenvalues $N \vec{u}_i = \lambda_i \vec{u}_i$ $\lambda_i = x_i + i y_i$

N^\dagger has eigenvalues $N^\dagger \vec{u}_i = \lambda_i^* \vec{u}_i$ $\lambda_i^* = x_i - i y_i$

The eigenvectors are orthogonal $\vec{u}_i \cdot \vec{u}_j = 0$ if $\lambda_i \neq \lambda_j$

so N has a unitary diagonalization

$$N = UDU^\dagger \quad \text{where} \quad U^\dagger U = I$$

Normal matrix analogy lists the special cases:

Hermitian: real eig's antiHermitian: imaginary
 Positive def: positive eig's Unitary: units $|\lambda_i|=1$

- Proof of simultaneous diagonalization:

$$\text{if } A\vec{v} = \lambda\vec{v} \quad AB = BA$$

$$\text{then } A(B\vec{v}) = B\lambda\vec{v} = \lambda(B\vec{v})$$

thus $B\vec{v} \in \lambda$ eigenspace Δ of A, λ

diagonalize B on Δ $B\vec{u} = \mu\vec{u}$

then $A\vec{u} = \lambda\vec{u}$ also,

- Proof of conjugate eigenvalues & unitary eigenvectors:

if $N\vec{u}_i = \lambda_i\vec{u}_i$ and $N^\dagger\vec{u}_i = \mu_i\vec{u}_i$ then

$$u_i^\dagger N^\dagger N u_j = (\lambda_i^* \lambda_j = \mu_i \lambda_j) u_i^\dagger u_j$$

if $i=j$ then $\lambda_i^* = \mu_i$

if $\lambda_i \neq \lambda_j$ then $u_i^\dagger u_j = 0$