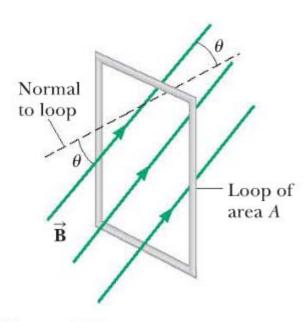
# Class 38 Power generator, eddy current, and self inductance

# Faraday's Law for motion emf: Example III



**Figure 31.3** A conducting loop that encloses an area A in the presence of a uniform magnetic field  $\vec{B}$ . The angle between  $\vec{B}$  and the normal to the loop is  $\theta$ .

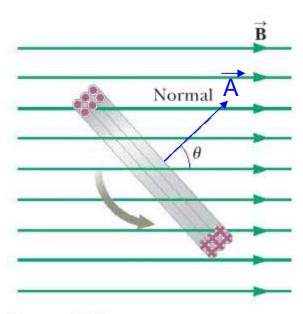
$$\varepsilon_{\text{loop}} = -\frac{d}{dt}\Phi_{\text{B}}$$

or 
$$\oint_{loop} \vec{E} \cdot d\vec{s} = -\frac{d}{dt} \left( \int_{loop} \vec{B} \cdot d\vec{A} \right)$$

#### Notes:

- 1.  $\epsilon_{loop}$  does not equal to 0 any more if  $d\Phi_{\rm B}/{\rm dt} \neq 0$
- 2. There are two ways to make  $d\Phi_B/dt \neq 0$ :
  - (i) Changing B
  - (ii) Changing A (loop shape)

## Faraday's Law for changing $\theta$ : Generator



**Figure 31.18** A cutaway view of a loop enclosing an area A and containing N turns, rotating with constant angular speed  $\omega$  in a magnetic field. The emf induced in the loop varies sinusoidally in time.

$$\theta = \omega t$$
  
 $\theta = 0$  at  $t = 0$ 

$$\oint_{\text{loop}} \vec{E} \cdot d\vec{s} = -\frac{d}{dt} \left( \int_{\text{B}} \vec{B} \cdot d\vec{A} \right)$$

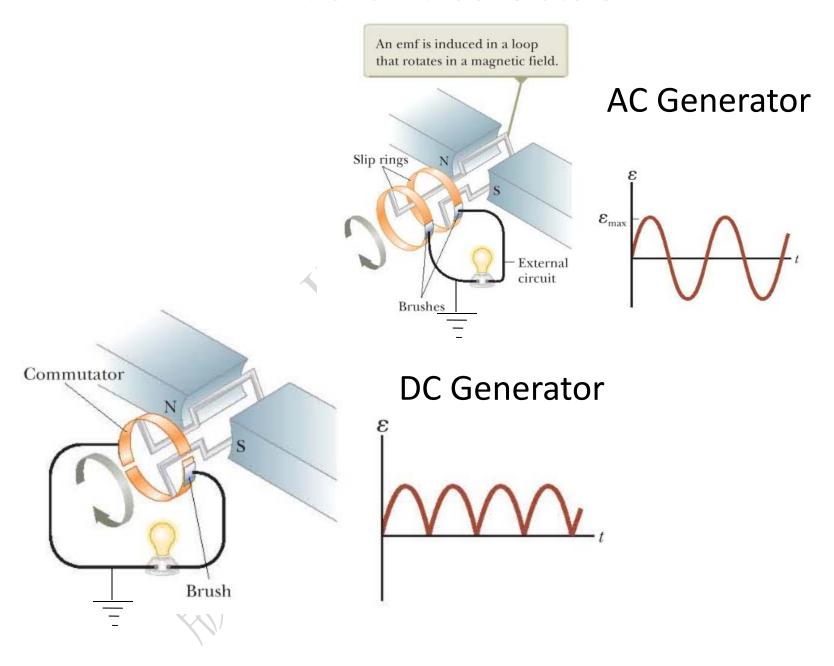
$$= -\frac{d}{dt} \left( \int_{\text{B}} \vec{B} \cdot N dA \cos \omega t \right)$$

$$= -\frac{d}{dt} \left( NBA \cos \omega t \right)$$

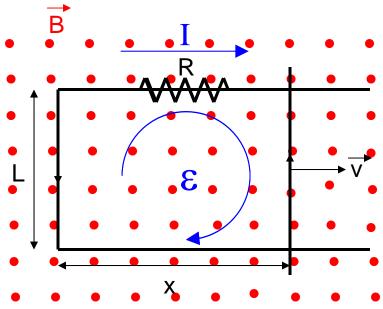
$$= NBA \omega \frac{d}{dt} \cos \omega t$$

$$\therefore \varepsilon = NBA\omega \sin \omega t$$

#### AC and DC Generators

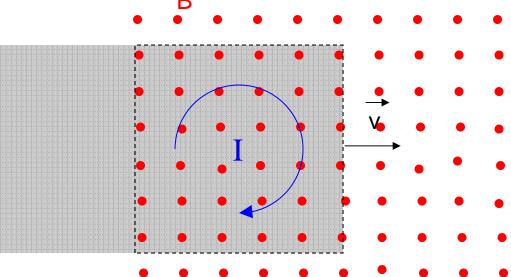


### **Eddy Current**

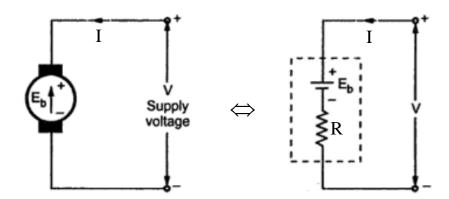


When a conductor moves in an inhomogeneous magnetic field, the induced emf will produce current flow in the conductor, called Eddy current.

Lenz's Law: The Eddy current will in turn produce a magnetic force in opposite direction to the velocity, like friction.



#### Electric motor and back emf



An electric motor behaves like a generator as it is rotating. This will generate an emf in opposite to the applied voltage, called back emf.

$$V = E_b + IR$$

Where R is the resistance of the windings. When the motor starts turning,  $E_b = 0$  and all power is dissipated as heat  $I_2R$  (wasted). When the motor is in full speed, mechanical power of the motor is  $IE_b$  and the power of the wasted heat will drop to  $(V-E_b)^2/R$ .