

Use the commutation relation between the operators x and p to obtain the equations describing the time dependence of $\langle x \rangle$ and $\langle p \rangle$ for the Hamiltonian given by

$$H = \frac{p^2}{2m} + \frac{1}{2}m(\omega_1^2 x^2 + \omega_2 x + C)$$

Solution:

$$\begin{aligned} \frac{d}{dt} \langle p \rangle &= \frac{i}{\hbar} \langle [H, p] \rangle \\ &= \frac{i}{\hbar} \langle [\frac{p^2}{2m} + \frac{1}{2}m(\omega_1^2 x^2 + \omega_2 x + C), p] \rangle \\ &= \frac{im}{2\hbar} \langle [(\omega_1^2 x^2 + \omega_2 x), p] \rangle \quad ([p^2, p] = 0 \text{ and } [C, p] = 0) \\ &= \frac{im}{2\hbar} \{ \langle \omega_1^2 [x^2, p] \rangle + \langle \omega_2 [x, p] \rangle \} \\ &= \frac{im}{2\hbar} \{ \langle \omega_1^2 (x[x, p] + [x, p]x) \rangle + \langle \omega_2 [x, p] \rangle \} \\ &= \frac{im}{2\hbar} \{ \langle \omega_1^2 (2i\hbar x) \rangle + \langle \omega_2 (i\hbar) \rangle \} \\ &= -\frac{m}{2} \{ \langle \omega_1^2 (2x) \rangle + \langle \omega_2 \rangle \} \\ &= -\frac{m}{2} \{ 2\omega_1^2 \langle x \rangle + \omega_2 \} \quad \text{--- (1)} \end{aligned}$$

$$\begin{aligned} \frac{d}{dt} \langle x \rangle &= \frac{i}{\hbar} \langle [H, x] \rangle \\ &= \frac{i}{\hbar} \langle [\frac{p^2}{2m} + \frac{1}{2}m(\omega_1^2 x^2 + \omega_2 x + C), x] \rangle \\ &= \frac{i}{\hbar} \langle [\frac{p^2}{2m}, x] \rangle \\ &= \frac{i}{2m\hbar} \langle [p^2, x] \rangle \\ &= \frac{i}{2m\hbar} \langle p[p, x] + [p, x]p \rangle \\ &= \frac{i}{2m\hbar} \langle -2i\hbar p \rangle \\ &= \frac{\langle p \rangle}{m} \quad \text{----(2)} \end{aligned}$$

Differentiating (1)

$$\begin{aligned} \therefore \frac{d^2}{dt^2} \langle p \rangle &= -\frac{m}{2} \left\{ 2\omega_1^2 \frac{d}{dt} \langle x \rangle \right\} \\ \Rightarrow \frac{d^2}{dt^2} \langle p \rangle &= -m \omega_1^2 \frac{d}{dt} \langle x \rangle \end{aligned} \quad \text{--- (3)}$$

Substitute (2) into (3)

$$\begin{aligned} \frac{d^2}{dt^2} \langle p \rangle &= -m \omega_1^2 \frac{\langle p \rangle}{m} \\ \Rightarrow \frac{d^2}{dt^2} \langle p \rangle &= -\omega_1^2 \langle p \rangle \\ \Rightarrow \underline{\underline{\langle p \rangle}} &= \underline{\underline{\langle p(0) \rangle e^{i\omega_1 t}}} \end{aligned}$$

From (2) :

$$\underline{\underline{\langle x \rangle}} = \underline{\underline{\frac{\langle p(0) \rangle}{m} e^{i\omega_1 t}}}$$