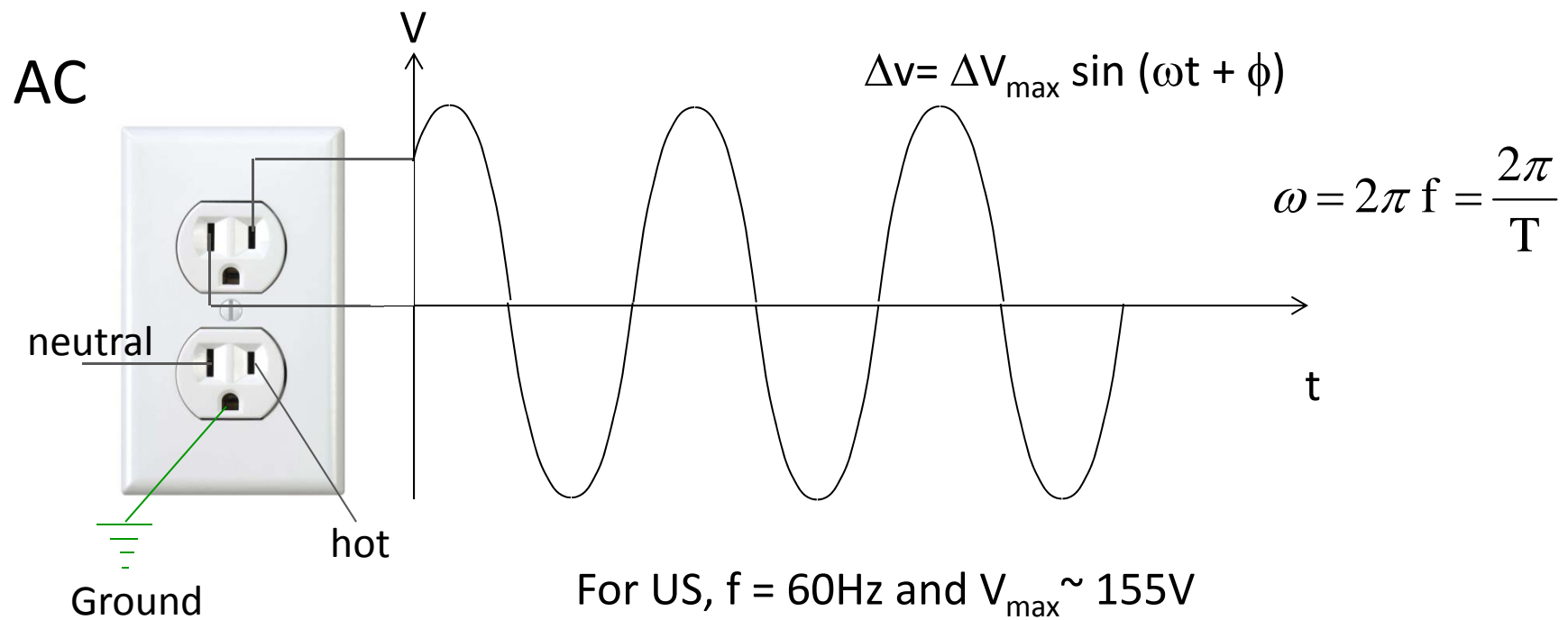
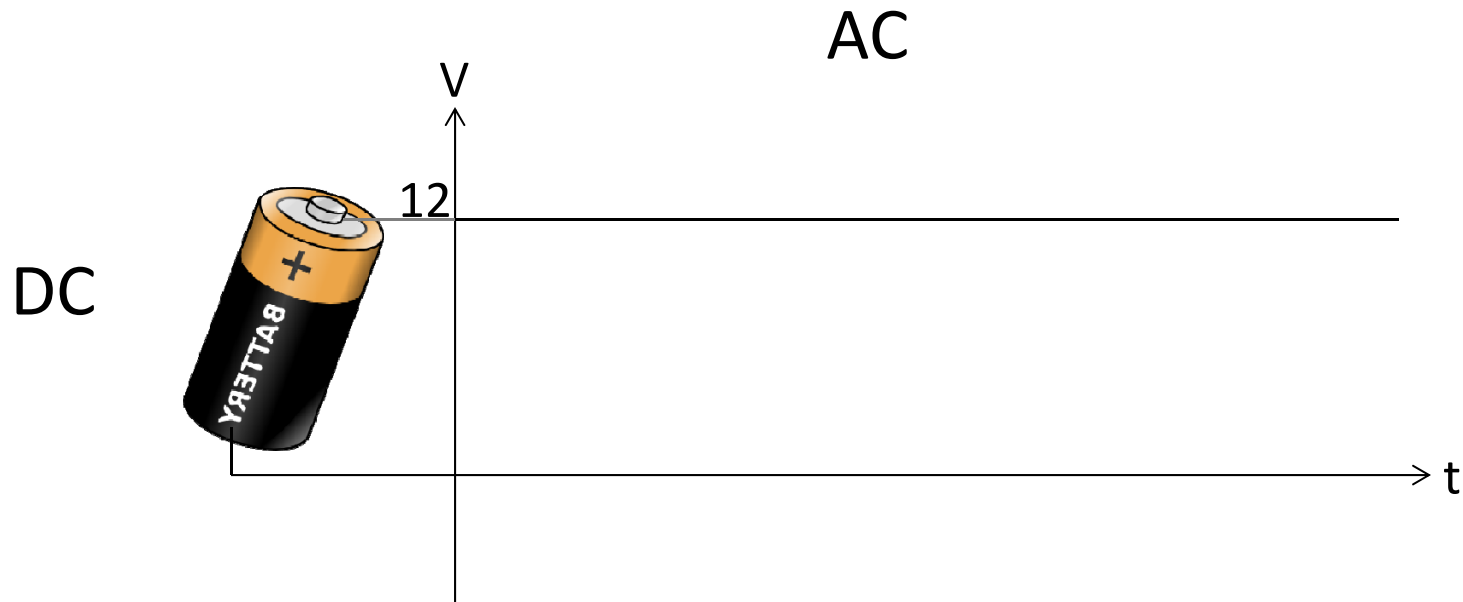
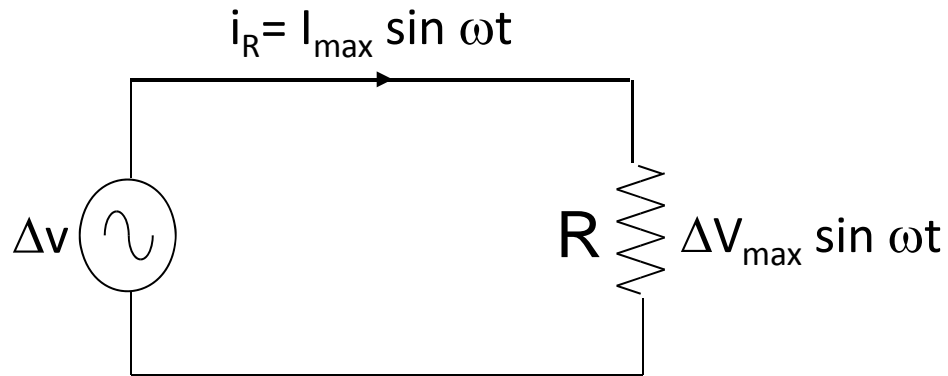


Class 37 Displacement currents



Power dissipated in a Resistor in an AC circuit

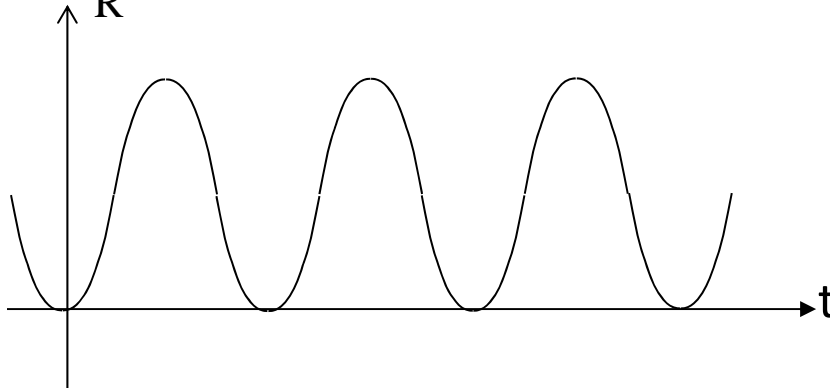


$$I_{\max} = \frac{\Delta V_{\max}}{R}$$

$$\Delta v = \Delta V_{\max} \sin \omega t$$

$$i_R = I_{\max} \sin \omega t$$

$$P = \frac{\Delta V_{\max}^2}{R} \sin^2 \omega t$$

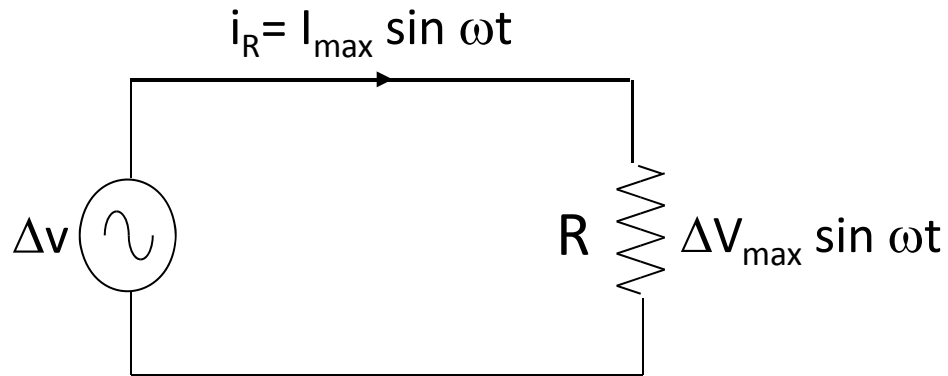


$$P = i_R \Delta v = \frac{\Delta V_{\max}^2}{R} \sin^2 \omega t$$

Average power dissipated in one period (T):

$$\begin{aligned} \langle P \rangle &= \frac{1}{T} \int_0^T \frac{\Delta V_{\max}^2}{R} \sin^2 \omega t \, dt \\ &= \frac{1}{2} \frac{\Delta V_{\max}^2}{R} \end{aligned}$$

Root Mean Square Voltage and Current

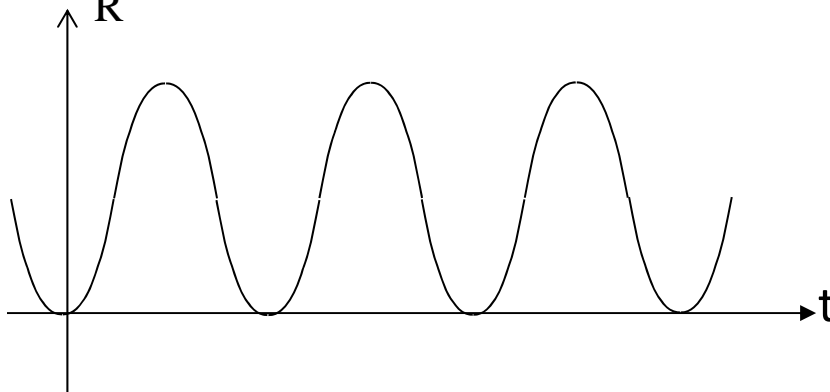


$$\langle P \rangle = \frac{1}{2} \frac{\Delta V_{\max}^2}{R}$$

$$\text{Define } \Delta V_{\text{rms}} = \frac{\Delta V_{\max}}{\sqrt{2}} \sim 0.707 V_{\max}$$

$$\langle P \rangle = \frac{\Delta V_{\text{rms}}^2}{R}$$

$$P = \frac{\Delta V_{\max}^2}{R} \sin^2 \omega t$$

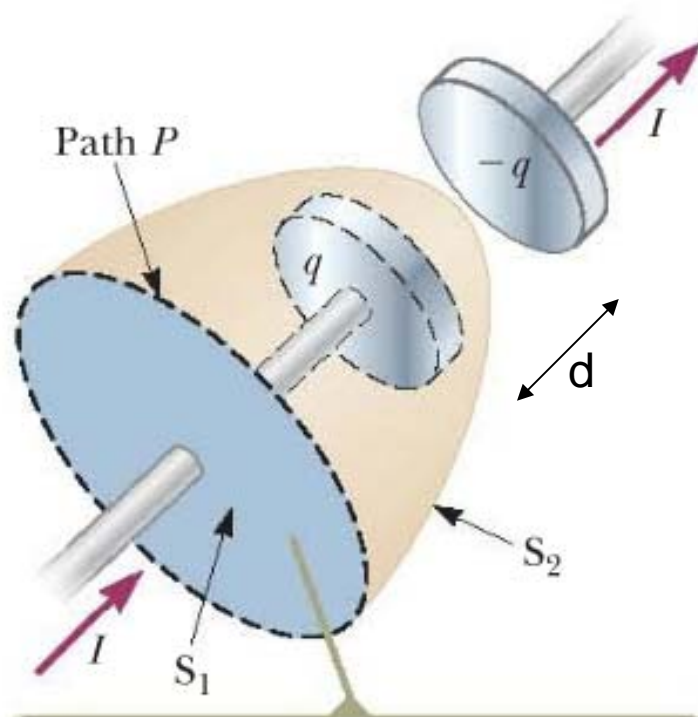


$$i_{\max} = \frac{V_{\max}}{R} \Rightarrow i_{\text{rms}} = \frac{V_{\text{rms}}}{R}$$

$$\text{with } i_{\text{rms}} = \frac{i_{\max}}{\sqrt{2}} \sim 0.707 i_{\max}$$

$$\langle P \rangle = i_{\text{rms}}^2 R$$

Revisit Ampere's Law



The conduction current I in the wire passes only through S_1 , which leads to a contradiction in Ampère's law that is resolved only if one postulates a displacement current through S_2 .

For DC, $I=0$ and $B=0$, so there is no problem.

If I is changing with time, $I \neq 0$ (except at the gap) and there will be a magnetic field (changing with time also).

If the gap d is very small ($d \rightarrow 0$), there should be magnetic field everywhere surrounding the wire even though there is no physical current through the gap.

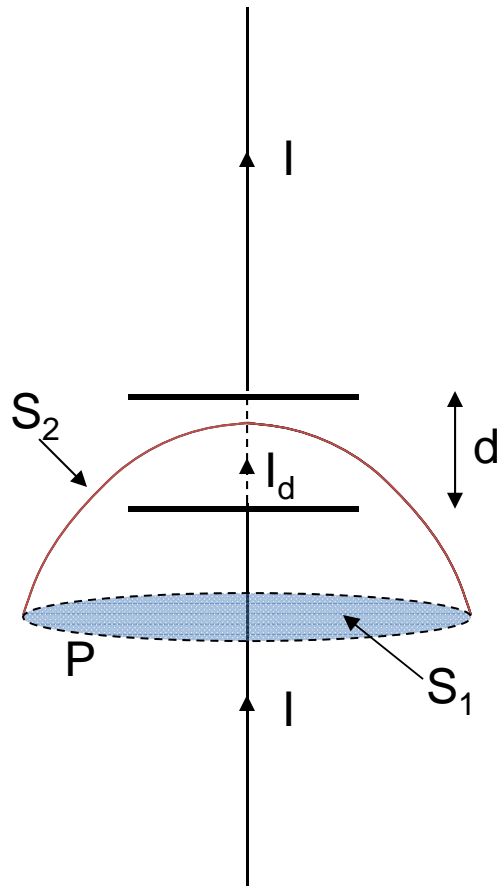
The problem now is:

$$\text{For surface } S_1 : \oint_{\text{Path P}} \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{Enclosed by } S_1} = \mu_0 I$$

$$\text{For surface } S_2 : \oint_{\text{Path P}} \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{Enclosed by } S_2} = 0$$

How to reconcile the difference?

Maxwell's proposal



We can introduce an imaginary current, called displacement current, I_d within the gap so the current now looks like continuous.

With this displacement current:

$$\text{For surface } S_1 : \oint_P \vec{B} \cdot d\vec{S} = \mu_0 I_{\text{Enclosed by } S_1} = \mu_0 I$$

$$\text{For surface } S_2 : \oint_P \vec{B} \cdot d\vec{S} = \mu_0 I_{\text{Enclosed by } S_2} = \mu_0 I_d = \mu_0 I$$

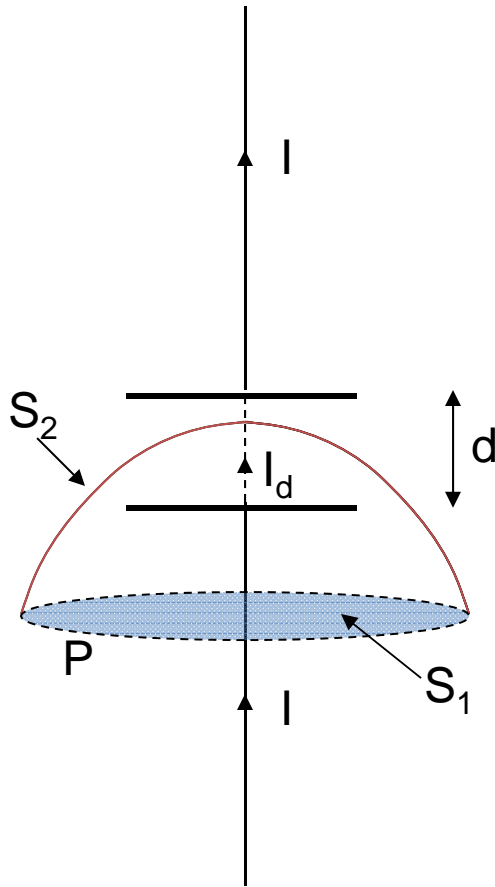
Ampere's Law now becomes:

$$\oint \vec{B} \cdot d\vec{S} = \mu_0 (I_{\text{Enclosed}_1} + I_d)$$

Displacement current

But at the end what is a displacement current?

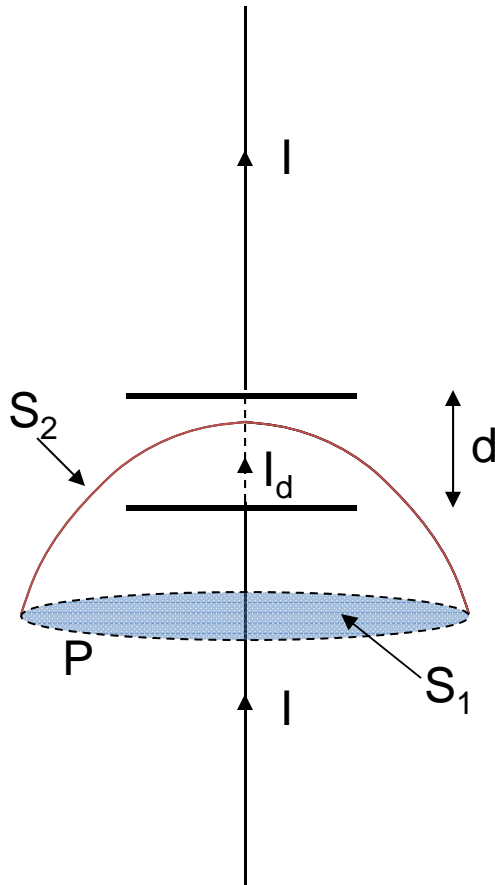
It is not a real current due to motion of charges within the gap, so we have to relate it to something that really exists in the gap: electric field.



$$\begin{aligned}
 I_d = I &= \frac{dq}{dt} = C \frac{dV}{dt} & (q = CV) \\
 &= Cd \frac{dE}{dt} & (V = Ed) \\
 &= \frac{\epsilon_0 A}{d} \cdot d \frac{dE}{dt} & (C = \frac{\epsilon_0 A}{d}) \\
 &= \epsilon_0 \frac{d(EA)}{dt} \\
 &= \epsilon_0 \frac{d\Phi_E}{dt}
 \end{aligned}$$

Abstraction

$$I_d = \epsilon_0 \frac{d\Phi_E}{dt}$$



We got this idea from parallel plate capacitor. We expand this and say this is generally true for any geometry and Ampere's Law now becomes:

$$\oint \vec{B} \cdot d\vec{S} = \mu_0 (I_{\text{Enclosed}} + \epsilon_0 \frac{d\Phi_E}{dt})$$

$$= \mu_0 (I_{\text{Enclosed}} + \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{A})$$

Maxwell's Equations

Maxwell's 1st equation: (Gauss's Law for electric field)

$$\epsilon_0 \oint \vec{E} \cdot d\vec{A} = q_{\text{in}}$$

Maxwell's 2nd equation: (Gauss's Law for magnetic field)

$$\oint \vec{B} \cdot d\vec{A} = 0$$

Maxwell's 3rd equation: (Faraday's Law)

$$\oint \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{A}$$

Maxwell's 4th equation: (Ampere's Law – Now complete)

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 (I_{\text{in}} + \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{A})$$

Note the symmetry
between these two
equations.

Maxwell's equations describe only the fields, it does not include the effect of the field on charges or currents:

$$\vec{F}_E = q\vec{E}$$

$$\vec{F}_B = q\vec{v} \times \vec{B} \quad (\text{or } d\vec{F}_B = Id\vec{s} \times \vec{B})$$

Not included in Maxwell's
equations

Maxwell's Equations

PHY 232:

$$\epsilon_0 \oint \vec{E} \cdot d\vec{S} = Q_{\text{in}}$$

$$\oint \vec{B} \cdot d\vec{S} = 0$$

$$\oint \vec{E} \cdot d\vec{\ell} + \frac{\partial}{\partial t} \oint \vec{B} \cdot d\vec{S} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} - \epsilon_0 \mu_0 \frac{\partial}{\partial t} \oint \vec{E} \cdot d\vec{S} = \mu_0 I_{\text{in}}$$

For most physicists /
engineers:

$$\epsilon_0 \nabla \cdot \vec{E} = \rho$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} + \frac{\partial}{\partial t} \vec{B} = 0$$

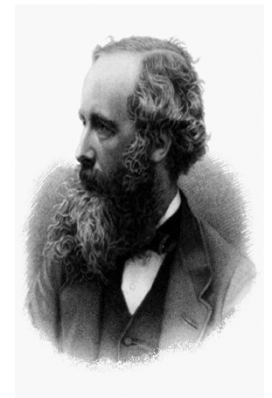
$$\frac{1}{\mu_0} \cdot \nabla \times \vec{B} - \epsilon_0 \frac{\partial}{\partial t} \vec{E} = \vec{J}$$

For theoretical physicists:

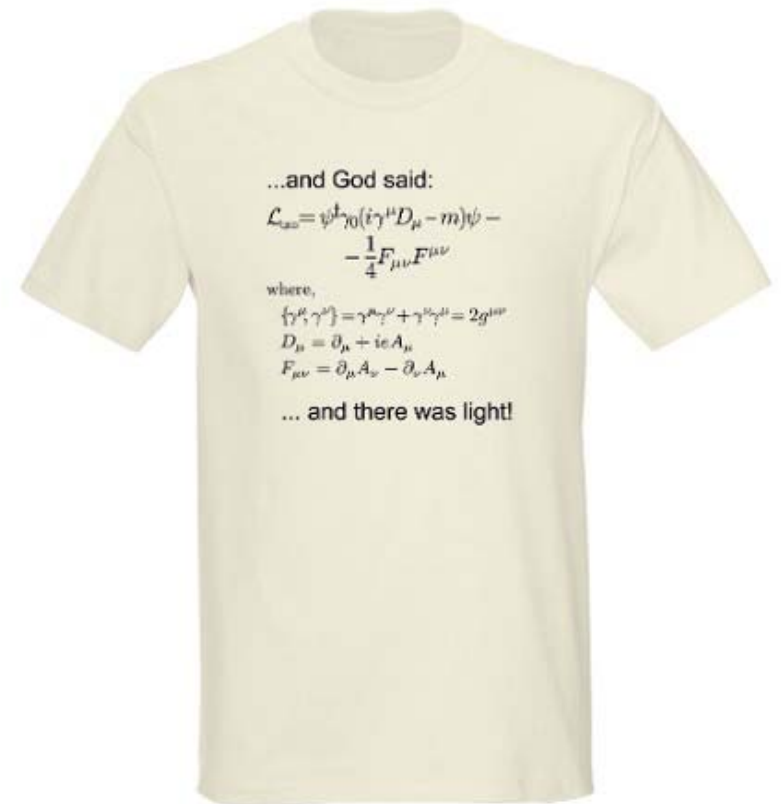
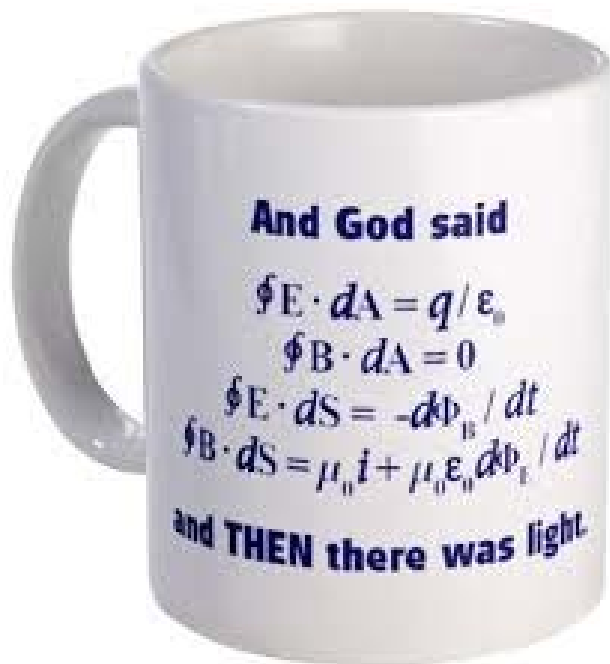
$$\partial_\alpha F^{\alpha\beta} = \frac{4\pi}{c} j^\beta$$

$$\partial_\alpha F_{\beta\gamma} + \partial_\beta F_{\gamma\alpha} + \partial_\gamma F_{\alpha\beta} = 0$$

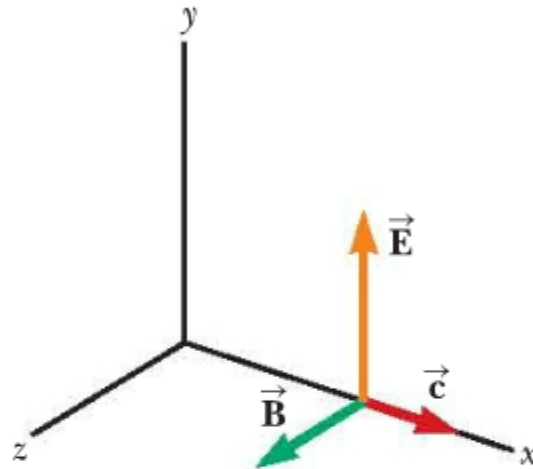
(Gaussian
units)



Three different forms of Maxwell's Equations



Linearly polarized electromagnetic Waves



ACTIVE FIGURE 34.5

Electric and magnetic fields of an electromagnetic wave traveling at velocity \vec{c} in the positive x direction. The field vectors are shown at one instant of time and at one position in space. These fields depend on x and t .

The wave is traveling in the $\vec{E} \times \vec{B}$ direction.

Linearly polarized waves

Applying Maxwell's Third Equation to Plane Electromagnetic Waves

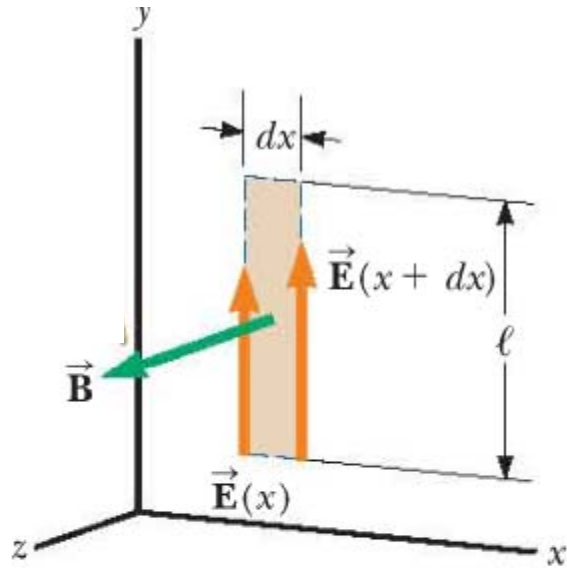


Figure 34.6 At an instant when a plane wave moving in the positive x direction passes through a rectangular path of width dx lying in the xy plane, the electric field in the y direction varies from $\vec{E}(x)$ to $\vec{E}(x + dx)$.

$$\oint \vec{E} \cdot d\vec{s} = - \frac{d}{dt} \iint \vec{B} \cdot d\vec{A}$$

$$\begin{aligned} \oint \vec{E} \cdot d\vec{s} &= E(x + dx)\ell + 0 - E(x)\ell + 0 \\ &= \ell[E(x + dx) - E(x)] \\ &= \ell \frac{\partial E}{\partial x} \cdot dx \end{aligned}$$

$$\begin{aligned} - \frac{d}{dt} \iint \vec{B} \cdot d\vec{A} &= - \frac{\partial}{\partial t} (B \cdot \ell dx) \\ &= - \ell \frac{\partial B}{\partial t} \cdot dx \end{aligned}$$

$$\therefore \frac{\partial E}{\partial x} = - \frac{\partial B}{\partial t}$$